

Semidefinite relaxations in non-convex spaces

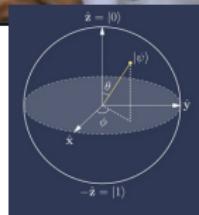
Alex Pozas-Kerstjens

mathQI - Universidad Complutense de Madrid



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Can I be sure that what I observe is quantum?



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Quantum models for observations

$p(a, b, \dots | x, y, \dots)$ is quantum $\Rightarrow \exists \rho \in \mathcal{H}, \{\Pi_{a|x}^A\}, \{\Pi_{b|y}^B\}, \dots$
such that $p(a, b, \dots | x, y, \dots) = \text{Tr} \left(\rho \Pi_{a|x}^A \Pi_{b|y}^B \dots \right)$

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$$\Rightarrow \forall \mathcal{S} = \{\Pi_{o|i}^P, \Pi_{o_1|i_1}^{P_1} \Pi_{o_2|i_2}^{P_2}, \dots\}$$

$$\Gamma | \Gamma_{i,j} = \text{Tr}(\rho S_i^\dagger S_j), S_i, S_j \in \mathcal{S}$$

$$\Gamma \succeq 0$$

The NPA hierarchy

$\mathcal{S}_n = \{\text{all products of operators of length } \leq n\}$

p is quantum $\Leftrightarrow \Gamma^{(n)} \succeq 0 \forall n$

p is not quantum $\Rightarrow \exists n^* \text{ such that } \Gamma^{(n \geq n^*)} \prec 0$

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In practice:

$$p(a, b, c, \dots | x, y, z, \dots) \stackrel{?}{=} \text{Tr}(\rho \Pi_{a|x}^A \Pi_{b|y}^B \dots)$$

1. Choose symbols that define

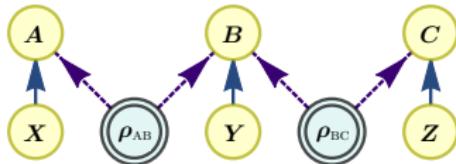
$$\mathcal{S} = \{\Pi_{o|i}^P, \Pi_{o_1|i_1}^{P_1} \Pi_{o_2|i_2}^{P_2}, \dots\}$$

2. Create $\Gamma|\Gamma_{i,j} = \text{Tr}(\rho S_i^\dagger S_j)$, $S_i, S_j \in \mathcal{S}$

3. Solve the SDP

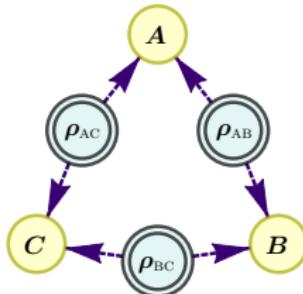
[find vars / optimize f] s.t. $\Gamma \succeq 0$

Restricting the set of possible ρ



$$\rho = \rho_{AB} \otimes \rho_{BC}$$

$$\sum_b p(a, b, c|x, y, z) = p(a|x)p(c|z)$$



$$\rho = \rho_{AB} \otimes \rho_{BC} \otimes \rho_{CA}$$

$\Gamma^{(n)} \succeq 0 \forall n$ if p is quantum,
but the feasible regions are not convex

Two SDP-compatible methods

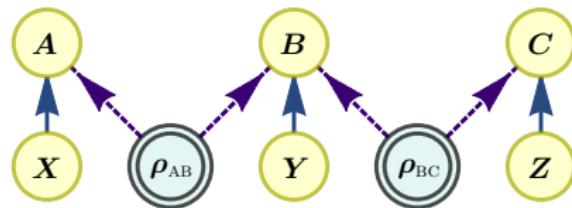
Scalar extension (Phys. Rev. Lett. 123, 140503)

- Independence constraints
- “Experimentally” powerful

Quantum inflation (Phys. Rev. X 11, 021043)

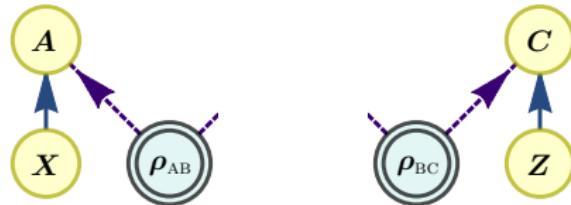
- More general non-convex spaces
- Precise notion of hierarchy

Scalar extension for independence constraints



$$p(a, b, c|x, y, z) = \text{Tr} \left(\rho_{AB_1} \otimes \rho_{B_2C} \Pi_{a|x}^A \Pi_{b|y}^B \Pi_{c|z}^C \right)$$

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$$\langle \Pi_{a_1}^A \dots \Pi_{a_k}^A \Pi_{c_1}^C \dots \Pi_{c_l}^C \rangle = \langle \Pi_{a_1}^A \dots \Pi_{a_k}^A \rangle \langle \Pi_{c_1}^C \dots \Pi_{c_l}^C \rangle$$

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Complement sets of generating monomials with operator strings
multiplied by scalars.

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$$\Gamma = \begin{pmatrix} \mathbb{1} & A_0 A_1 & C_0 C_1 & \langle A_0 A_1 \rangle \mathbb{1} \\ (A_0 A_1)^\dagger & 1 & v_1 & v_2 & v_1 \\ (C_0 C_1)^\dagger & & 1 & v_3 & v_4 \\ \langle A_0 A_1 \rangle^* \mathbb{1} & & & 1 & v_5 \\ & & & & v_4 \end{pmatrix}$$

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$$\langle A_0 A_1 C_0 C_1 \rangle = \langle A_0 A_1 \rangle \langle C_0 C_1 \rangle$$

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⇓

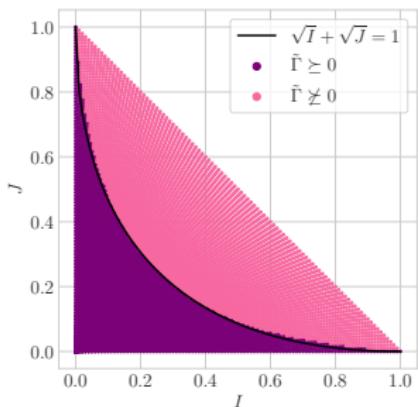
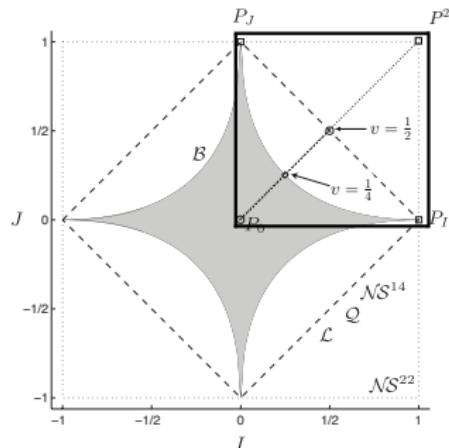
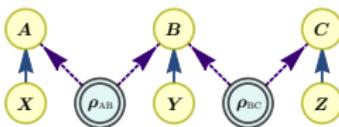
$$-1 \leq v_1 \leq 1$$

$$-1 \leq v_2 \leq 1$$

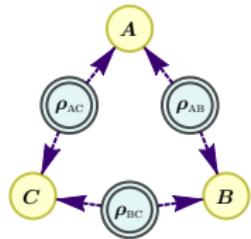
$$v_1^2 \leq v_4 \leq 1$$

$$v_1 v_2 - \sqrt{(v_4 - v_1^2)(1 - v_2^2)} \leq v_3 \leq v_1 v_2 + \sqrt{(v_4 - v_1^2)(1 - v_2^2)}$$

Approximations are tight in certain situations

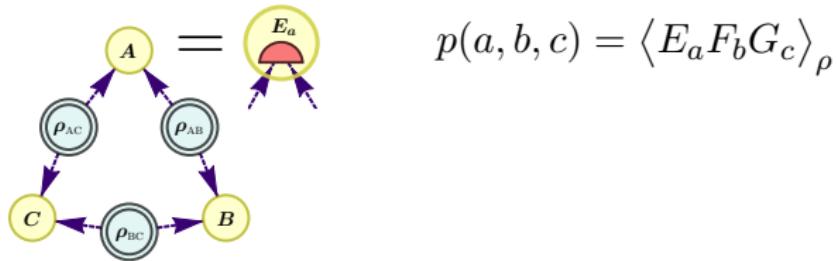


Quantum inflation for subtler nonconvexities



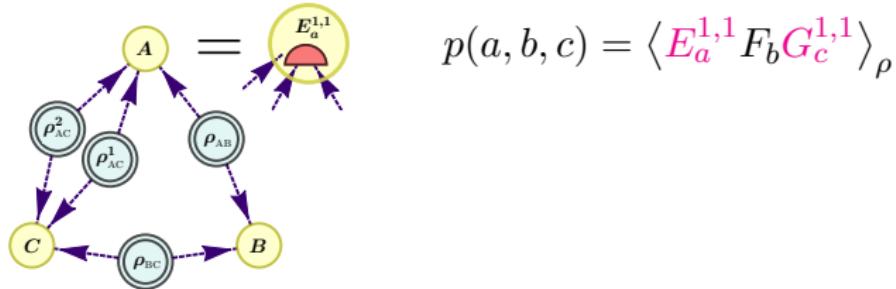
Quantum inflation for subtler nonconvexities

$$\rho = \rho_{AB} \otimes \rho_{BC} \otimes \rho_{AC}$$



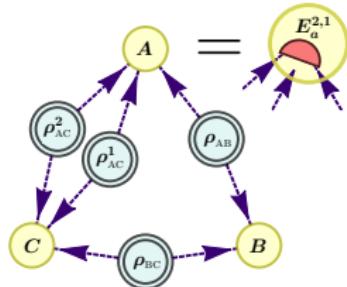
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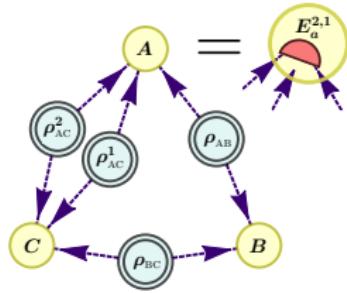
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$$\begin{aligned} p(a, b, c) &= \langle E_a^{1,1} F_b G_c^{1,1} \rangle_\rho \\ &= \langle E_a^{2,1} F_b G_c^{1,2} \rangle_\rho \end{aligned}$$

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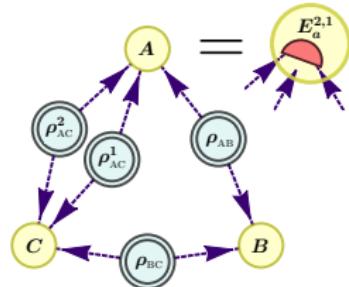
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$\exists \rho$

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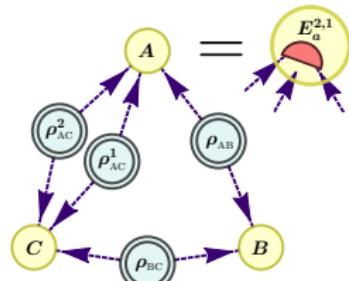
Can be solved with the NPA hierarchy

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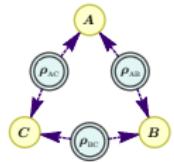


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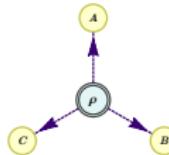
Can be solved with the NPA hierarchy

Inflation hierarchy ($m = \#$ copies) + NPA hierarchy for each m

Application 1: Constrained optimization



vs.



Mermin

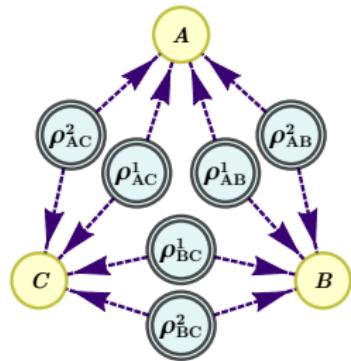
$$\langle A_1 B_0 C_0 \rangle + \langle A_0 B_1 C_0 \rangle + \langle A_0 B_0 C_1 \rangle - \langle A_1 B_1 C_1 \rangle \leq \begin{cases} 3.085^* & Q^\Delta \\ 4 & Q \end{cases}$$

Svetlichny

$$\begin{aligned} \langle A_1 B_0 C_0 \rangle + \langle A_0 B_1 C_0 \rangle + \langle A_0 B_0 C_1 \rangle - \langle A_1 B_1 C_1 \rangle \\ - \langle A_0 B_1 C_1 \rangle - \langle A_1 B_0 C_1 \rangle - \langle A_1 B_1 C_0 \rangle + \langle A_0 B_0 C_0 \rangle \leq \begin{cases} 4.405^* & Q^\Delta \\ 4\sqrt{2} & Q \end{cases} \end{aligned}$$

Application 2: Optimization of polynomial objectives

Example: distance to a given distribution p_t



$$\begin{aligned} f(p) &= \sum_{a,b,c} |p(a, b, c) - p_t(a, b, c)|^2 \\ &= \sum_{a,b,c} [p(a, b, c)p(a, b, c) \\ &\quad - 2p_t(a, b, c)p(a, b, c)] + \text{const} \\ &= \sum_{a,b,c} \left[\langle E_a^{1,1} E_a^{2,2} F_b^{1,1} F_b^{2,2} G_c^{1,1} G_c^{2,2} \rangle_\rho \right. \\ &\quad \left. - 2p_t(a, b, c) \langle E_a^{1,1} F_b^{1,1} G_c^{1,1} \rangle_\rho \right] + \text{const} \end{aligned}$$

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Main idea	NPA + new symbols for nonlinear operators	Copies of the scenario + NPA
Good for	Factorizations	Latent tensor products
Strengths	More efficient Probably more useful outside QI	(Much) more general Optimization of polynomial objectives
Weaknesses	Optimization of polynomial objectives	Computationally demanding

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Open questions	- Convergence (arXiv:2006.12510) - Smart choice of \mathcal{S}	- Convergence (arXiv:1707.06476, arXiv:1911.11056) - Smart choice of \mathcal{S} - Hierarchy balance

Thank you for your attention

Questions? Comments?



1904.08943 / PRL 123, 140503 (2019)
1909.10519 / PRX 11, 021043 (2021)

Scalar Extension
Quantum Inflation



physics@alexpozas.com



apozas/quantum-networks-scalar-extension

mathQI



Horizon 2020
European Union funding
for Research & Innovation

This project has received funding from the European Research Council (ERC) under the
European Union's Horizon 2020 research and innovation programme (grant agreement No 648913)