

Upscaling and spatial localization of non-local energies with applications to crystal plasticity

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8ECM

Nonlinear analysis for continuum mechanics (MS -33)

June 25, 2021

Structured deformations

First order (Del Piero, Owen)

The model sets a basis to address problems in non-classical deformations of continua (for instance, study of equilibrium configurations of crystals with defects) where an analysis at **macroscopic** and **microscopic** levels is required, dividing the study of deformations in two parts: the part arising from **smooth changes** and the part due to **slips and separations (disarrangements)** at smaller length scales.



S.D. pair(g, G)

with $f_n \xrightarrow{L^\infty} g$, $\nabla f_n \xrightarrow{L^\infty} G$, and with f_n injective.

▶ g accounts for the *macroscopic change in geometry*.

$$M := \nabla g - G$$

is attained through **slips** and **separations (disarrangements)** that take place at a smaller length scale.

Example *Deck of cards*

$$N = 2, \Omega = (0, 1)^2,$$

$$g(x_1, x_2) = (x_1 + x_2, x_2), \text{ (simple shear) } G = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$f_n(x) = (x_1 + \frac{k}{n}, x_2), \frac{k}{n} \leq x_2 < \frac{k+1}{n}, k = 0, \dots, n-1$$

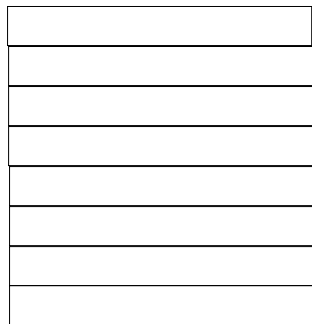
$$f_n \xrightarrow{L^\infty} g, \nabla f_n \xrightarrow{L^\infty} G, Df_n \rightarrow \nabla g = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$M = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

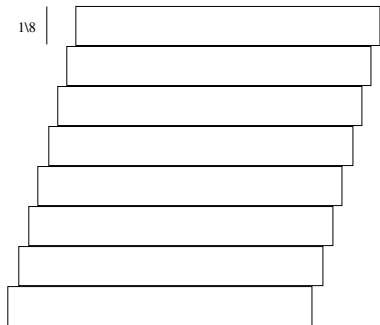
Example

Deck of cards

f_8



1



d

Integral representation (SBV framework)

The energy associated with the structured deformation (g, G) can be defined as the **most economical way** to build up the pair using approximations in *SBV*:

$$I_L(g, G) = \inf_{u_n \in SBV(\Omega; \mathbb{R}^d)} \left\{ \liminf_{n \rightarrow \infty} E_L(u_n), u_n \xrightarrow{L^1} g, \nabla u_n \xrightarrow{L^p} G \right\} \quad (1)$$

for $(g, G) \in SBV(\Omega; \mathbb{R}^d) \times L^p(\Omega; \mathbb{R}^{d \times N})$, $p \geq 1$, with

$$E_L(v) = \int_{\Omega} W(x, \nabla v) dx + \int_{S_v} \psi(x, [v], \nu_v) d\mathcal{H}^{N-1}, \quad (2)$$

$$v \in SBV(\Omega; \mathbb{R}^d)$$

Integral representation result in CF

- ▶ Under appropriate assumptions (among which **linear growth** of ψ), $I_L(g, G)$ admits an integral representation of the form:

$$I_L(g, G) = \int_{\Omega} H(x, \nabla g, G) dx + \int_{S(g)} h(x, [g], \nu_{(g)}) d\mathcal{H}^{N-1},$$

with H and h defined through appropriate cell formulae.

- ▶ The relaxed bulk energy density H depends **both** on W and ψ .
- ▶ In this work we extend the original result in CF, by allowing **explicit** dependence on the variable x .

Motivation of our work

The theory of structured deformation in the SBV setting developed by Choksi & Fonseca only takes into account the **linear dependence** on jumps along the approximating sequences. Del Piero & Owen proposed a 1-D model toward capturing the non-linear dependence on the jumps. The idea was to modify the initial energy as follows: for each $r \in (0, 1)$ let

$$F^r(u) = \int_0^1 W(u'(x)) dx + \sum_{z \in S_u} \psi([u](z)) \\ + \int_0^1 \Psi \left(\sum_{z \in S_u \cap (x-r, x+r)} \frac{[u](z)}{2r} \right) dx,$$

and then undergo a relaxation process in the context of structured deformations followed by taking the limit as $r \rightarrow 0^+$.

Framework

The present approach to relaxation of non-local energies rests on **two** limiting processes:

1. Start from a submacroscopical level where we have a **weighted average of disarrangements** within neighborhoods of fixed size $r > 0$ and pass to the macrolevel, permitting disarrangements to diffuse through such a neighborhood. This limiting process determines a structured deformation as well as the non-local dependence of the energy density of such a structured deformation.
2. Pass to the **limit as $r \rightarrow 0$** , to obtain purely local bulk and interfacial energy densities for the structured deformation identified in the first step.

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Averaging processes

Let $\Omega \subset \mathbb{R}^N$ a bounded connected open set with Lipschitz boundary $\partial\Omega$ and $u \in SBV(\Omega; \mathbb{R}^d)$. For a continuous function $\Psi: \Omega \times \mathbb{R}^{d \times N} \rightarrow [0, +\infty)$ and fixed $r > 0$ we define the **non-local** contribution by

$$E^{\alpha_r}(u) := \int_{\Omega_r} \Psi(x, (D^s u * \alpha_r)(x)) dx, \quad (3)$$

where $\Omega_r := \{x \in \Omega : \text{dist}(x; \partial\Omega) > r\}$.

Averaging processes

In (3)

$$\alpha_r := \frac{1}{r^N} \alpha\left(\frac{x}{r}\right),$$

where

$$\alpha \in C_c^\infty(B_1)$$

with

$$\int_{B_1} \alpha(x) dx = 1, \quad \alpha \geq 0, \quad \alpha(-x) = \alpha(x)$$

The symbol $*$ denotes the convolution operation.

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Averaging processes

Given $(g, G) \in SD(\Omega; \mathbb{R}^d)$, let $\{u_n\} \subset SBV(\Omega; \mathbb{R}^d)$ such that

(a) $u_n \rightarrow g$ in L^1 , $\nabla u_n \rightharpoonup G$ in L^p ($\overset{*}{\rightharpoonup}$ in L^1),

(b) $D^s u_n \overset{*}{\rightharpoonup} (\nabla g - G)\mathcal{L}^N + D^s g$ in $\mathcal{M}^+(\Omega)$,

We will denote by $Ad(g, G)$ the class of sequences satisfying (a) and (b).

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Averaging processes - the limit in n

We take the limit as $n \rightarrow \infty$ of $E^{\alpha_r}(u_n)$, obtaining

$$\begin{aligned} I_{NL}^r(g, G) &:= \lim_{n \rightarrow \infty} E^{\alpha_r}(u_n) \\ &= \lim_{n \rightarrow \infty} \int_{\Omega_r} \Psi(x, (D^s u_n * \alpha_r)(x)) \, dx \\ &= \int_{\Omega_r} \Psi\left(x, ((\nabla g - G)\mathcal{L}^N + D^s g) * \alpha_r\right) \, dx \end{aligned} \tag{4}$$

Averaging processes

We consider now an extension of (g, G) to $(\tilde{g}, \tilde{G}) \in \mathbb{R}^N \times \mathbb{R}^{d \times N}$ in the following sense:

$$(e1) \quad (\tilde{g}, \tilde{G})|_{\Omega} = (g, G),$$

$$(e2) \quad |D\tilde{g}|(\mathbb{R}^N) \leq C \|g\|_{BV(\Omega; \mathbb{R}^d)},$$

$$(e3) \quad |D\tilde{g}|(\partial\Omega) = 0.$$

Averaging processes

For such (\tilde{g}, \tilde{G}) , we extend $I_{NL}^r(g, G)$ to Ω by defining:

$$\begin{aligned} \tilde{I}_{NL}^r(\tilde{g}, \tilde{G}) &:= \int_{\Omega_r} \Psi(x, ((\nabla g - G)\mathcal{L}^N + D^s g) * \alpha_r) dx \\ &+ \int_{\Omega \setminus \Omega_r} \Psi(x, ((\nabla \tilde{g} - \tilde{G})\mathcal{L}^N + D^s \tilde{g}) * \alpha_r) dx \end{aligned} \quad (5)$$

In any case, independently of the extension considered, we can show that the difference between $I_{NL}^r(g, G)$ and $\tilde{I}_{NL}^r(\tilde{g}, \tilde{G})$ goes to zero as $r \rightarrow 0^+$.

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The limit as $r \rightarrow 0^+$

We work with $\tilde{I}_{NL}^r(\tilde{g}, \tilde{G})$ where Ψ can be of two types:

E) $\Psi \in C(\Omega \times \mathbb{R}^{d \times N})$ and $\Psi^\infty(x, \xi) := \lim_{\substack{x' \rightarrow x \\ \xi' \rightarrow \xi \\ t \rightarrow +\infty}} \frac{\Psi(x', t\xi')}{t}$ exists

in $\bar{\Omega} \times \mathbb{R}^{d \times N}$

L) $\Psi \in C(\Omega \times \mathbb{R}^{d \times N})$, Lipschitz continuous in the second variable with Ψ^∞ defined as $\Psi^\infty(x, \xi) := \limsup_{\substack{x' \rightarrow x \\ \xi' \rightarrow \xi \\ t \rightarrow +\infty}} \frac{\Psi(x', t\xi')}{t}$

We address the dependence in x with some modulus of continuity assumption on the first variable. The proof relies in [Reshetnyak continuity \(upper semicontinuity\) theorems](#).

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The limit as $r \rightarrow 0^+$

We have that, for any $(g, G) \in SD(\Omega; \mathbb{R}^d)$,

$$I_{NL}(g, G) := \lim_{r \rightarrow 0^+} \tilde{I}_{NL}^{\alpha_r}(\bar{g}, \bar{G}) = \int_{\Omega} \Psi(x, (\nabla g - G)(x)) \, dx \\ + \int_{\Omega \cap S(g)} \Psi^{\infty}\left(x, \frac{dD^s g}{d|D^s g|}(x)\right) \, d|D^s g|$$

Coupling

- ▶ $I(g, G) = I_L(g, G) + I_{NL}(g, G)$ where

$$I_L(g, G) = \int_{\Omega} H(x, \nabla g(x), G(x)) dx + \int_{S_{(g)} \cap \Omega} h(x, [g](x), \nu_{(g)}(x)) d\mathcal{H}^{N-1}$$

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Example from crystal plasticity

- ▶ **Crystallographic slip**: The discontinuity in deformation arises only across a limited family of slip planes.
- ▶ For a single crystal in the reference configuration Ω the data required for the analysis of crystallographic slip consists of **pairs of orthogonal unit vectors** (s^a, m^a) for $a = 1, \dots, A$, with A **the number of potentially active slip systems**.
- ▶ The unit vector s^a provides the **direction of slip**, while the unit vector m^a is a **normal to the slip plane** for the a^{th} slip-system (s^a, m^a) .

Crystallographic structured deformation

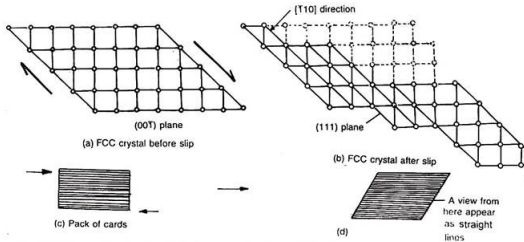


Fig. 6.15. Slip resembles distortion of deck of playing cards when pushed as shown (c & d). (a) FCC Crystal before slip, (b) FCC crystal after slip, (c) Pack of cards, (d) Pack of cards after slip.

Slip-neutral two level shears

Crystallographic slip is physically activated within very thin bands, (**slip-bands**) with thickness typically of the order 10^2 atomic units, while the separation of active slip-bands is typically of order 10^4 atomic units. Following [CDPFO1999], for each $a = 1, \dots, A$, there is a number $p^a > 0$ such that a **two-level shear** $(g_{\mu, x_0}^a, G_{\nu}^a)$ for which the shear due to slip $\mu - \gamma$ satisfies

$$\mu - \gamma = mp^a \quad \text{with } m \in \mathbb{Z} \quad (6)$$

and gives rise to **submacroscopic slips** equal to an integral number of atomic units in the direction of slip s^a .

Special properties for Ψ , under crystallographic slip

- ▶ This leads to the conclusion that, the **non-local** relaxed bulk density, in the context of crystal plasticity, can have **periodicity properties**, provided that it is restricted to each member of a family of two-dimensional affine subspaces of $\mathbb{R}^{3 \times 3}$, with (vector) period depending on the corresponding subspace.
- ▶ The periodicity stems from the fact that special families of two-level shears associated with the slip systems of the crystal are **geometrically undetectable**.

Thank you for your attention!