## Numerical scheme for an equation on a graph for a flow in a tube structure

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## Fluid in a network of thin tubes



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3

2 / 26

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- $O_1, O_2, \ldots, O_N$  vertices,  $\omega_1, \ldots, \omega_N \subset \mathbb{R}^3$  bounded open sets such that  $(0, 0, 0) \in \omega_n$ .
- For  $m \in \{1, \ldots, M\}$ , define the edge  $e_m = [O_{i_m}, O_{k_m}]$  of length  $l_m$ .
- $\mathcal{R}_m$  displacements such that  $\mathcal{R}_m(0,0,0) = \mathit{O}_{i_m}, \mathcal{R}_m(\mathit{I}_m,0,0) = \mathit{O}_{k_m}.$

•  $\sigma_1, \ldots, \sigma_M \subset \mathbb{R}^2$  bounded open sets.

Assume that  $\Omega = \bigcup_{m=1}^{M} \mathcal{R}_m(]0, I_m[\times \varepsilon \sigma_m) \cup \bigcup_{n=1}^{N} (O_n + \varepsilon \omega_n)$  is smooth for small  $\varepsilon$  except at the ends of unconnected tubes.

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## Navier-Stokes equations

 $\begin{cases} u = 0\\ u = g^{(e_i)}\\ \operatorname{div} u = 0 & \operatorname{on} \\ \frac{\partial u}{\partial t} + (u \cdot \nabla)u - \nu \Delta u = \frac{f - \nabla p}{\rho_0} & \operatorname{on} \Omega\\ u(., 0) = 0 & \operatorname{on} f \end{cases}$ 

on walls of tubes and junctions on unconnected end of tube *e*; (1)

- The width of the pipes scales as  $\varepsilon$ .
- The time scales as  $\varepsilon$
- The norms in  $W^{2,\infty}L^2$ ,  $W^{1,\infty}H^1$ ,  $L^{\infty}H^2$  of the velocity at the extremities of the network scale as  $\varepsilon^{\frac{n-1}{2}}$ ,  $\varepsilon^{\frac{n-3}{2}}$ ,  $\varepsilon^{\frac{n-5}{2}}$ .

Studied in:

Panasenko & Pileckas 2014, 2015, 2015

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4 / 26

(a)

## Flow in an infinite thin tube $\Omega = \mathbb{R} \times \sigma$ (Pileckas 2006)



Let us seek solution in the form  $u(x, y, z, t) = V(y, z, t)\vec{e}_x$  and p(x, y, z, t) = q(t)x + r(t).

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## Pressure gradient - flux operator

Let 
$$L^{(\sigma)}$$
: 
$$\begin{cases} L^2(0,\infty) \to H^1_0(0,\infty) \\ L^{(\sigma)}q = \Phi = \int_{\sigma} V = \int_0^t K^{(\sigma)}(t-\tau)q(\tau) \mathrm{d}t \end{cases}$$
 be the operator

connecting the pressure gradient to the flux through the pipe, where:

$$\begin{cases} \frac{\partial U}{\partial t} - \nu \Delta_{y,z} U = 0 & \text{on } \sigma \\ U(.,0) = \frac{1}{\rho_0} & \text{on } \sigma \\ U = 0 & \text{on } \partial \sigma \\ K(t) = \int_{\sigma} U(.,t) \end{cases}$$



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### Flow in a web of thin tubes



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## Flow in a net of tubes

Assumptions:

- $\Psi \in H^1_{00}(0, T)^N$  and  $f \in H^1_{00}(0, T, L^2(\mathcal{B}))$ . (The subscript 00 means that  $\Psi, f$  are zero at initial time)
- $\int_{\mathcal{B}} f + \sum_{I=1}^{N} \Psi_I = 0$

The fluid in the net of tubes can be approximated by:

$$\begin{cases} \Psi_n(t) + \sum_{\substack{[O_n, O_{\bar{n}}] = e_m \\ -\frac{\partial}{\partial x} L^{(\sigma_m)} \frac{\partial}{\partial x} p = f \text{ on } e_m \\ p \text{ continuous on } \mathcal{B} \\ p(O_1, t) = 0 \end{cases}$$
 (Kirchoff condition)

where  $D_{\vec{v}}$  denotes the directionnal derivative along  $\vec{v}$  and  $(L^{(\sigma_m)}q)(t) = \int_0^t \mathcal{K}^{(\sigma_m)}(t-\tau)q(\tau) \mathrm{d}t$ . Kirchoff condition expresses that the sum of the fluxes arriving from tube m at a junction n should be zero.

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## Graph discretization



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## Finite difference scheme

Let 
$$P_{s,q}^{(e)}$$
 be an approximation of  $P(X_s^{(e)}, t_q + \frac{k}{2})$ . Consider:  

$$\Psi_{\ell}(t_{q+1}) = \sum_{\substack{1 \le j \le M \\ 1 \le j \le M \\ q = 0}} \left[ \frac{-h^{(e_j)}}{2} F(X_s^{(e_j)} t_{q+1}) - k \sum_{\tilde{q}=0}^{q} \frac{\kappa_{q-\tilde{q}}^{(\sigma_j)}}{h^{(e_j)}} \frac{P_{\tilde{s},\tilde{q}}^{(e_j)} - P_{s,\tilde{q}}^{(e_j)}}{h^{(e_j)}} \right] \text{ if } \begin{cases} 2 \le \ell \le N \\ 0 \le q < Q \end{cases},$$

$$x_s^{(e_j)} = 0_{\ell} \in e_j,$$

$$|s-\tilde{s}| = 1, 0 \le \tilde{s} \le S^{(e_j)} \end{cases}$$

$$\begin{split} F(X_{s}^{(e_{j})},t_{q+1}) &= -k \sum_{\tilde{q}=0}^{q} \mathcal{K}_{q-\tilde{q}}^{(\sigma_{j})} \frac{P_{s+1,\tilde{q}}^{(e_{j})} - 2P_{s,\tilde{q}}^{(e_{j})} + P_{s-1,\tilde{q}}^{(e_{j})}}{(h^{(e_{j})})^{2}} \text{ if } \begin{cases} 1 \leq j \leq M \\ 0 < s < S^{(e_{j})} \\ 0 \leq q < Q \end{cases} \\ P_{s,q}^{(e)} &= P_{\tilde{s},q}^{(\tilde{e})} \text{ if } X_{s}^{(e)} = X_{\tilde{s}}^{(\tilde{e})}, 0 \leq q \leq Q, \\ P_{0,q}^{(e)} &= 0 \text{ if } X_{0}^{(e)} = O_{1}, 0 \leq q \leq Q, \\ P_{0,q}^{(e)} &= 0 \text{ if } X_{0}^{(e)} = O_{1}, 0 \leq q \leq Q, \\ \text{where } \mathcal{K}_{q}^{(\sigma_{j})} \simeq \frac{1}{k} \int_{t_{q}}^{t_{q+1}} \mathcal{K}^{(\sigma_{j})}(t) dt \text{ for } 0 \leq q \leq Q, 1 \leq j \leq M. \end{split}$$

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Image: A matrix

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## Accuracy of the kernel approximation

In order to measure the accuracy of the approximation of the discretized kernel  $(\mathcal{K}_q^{(\sigma)})_q$ , let us introduce:

$$\theta(k) = \max_{1 \le j \le M} |\mathcal{K}_0^{(\sigma_j)} - \frac{1}{k} \int_0^k \mathcal{K}^{(\sigma_j)}(t) dt| \\ + \sum_{q=1}^{Q-1} |\mathcal{K}_q^{(\sigma_j)} - \mathcal{K}_{q-1}^{(\sigma_j)} - \frac{1}{k} \int_{t_q}^{t_{q+1}} \mathcal{K}^{(\sigma_j)}(t) - \mathcal{K}^{(\sigma_j)}(t-k) dt|$$

Notice that it is a kind of discrete  $W^{1,1}$  norm.

## Weak form

• Let  $p, \psi \in L^2(0, T, H^1(\mathcal{B}))$ . Let us denote:

$$a(p,\psi) = \int_{[0,T]\times\mathcal{B}} \frac{\partial^2(\mathcal{L}^{(\overline{\sigma})}p)}{\partial x \partial \tau} \frac{\partial \psi}{\partial x}$$
$$b(\psi) = \int_{[0,T]\times\mathcal{B}} \frac{\partial f}{\partial \tau} \psi + \int_0^T \sum_{n=1}^N \frac{\partial \Psi_n}{\partial \tau} \psi(\mathcal{O}_n, .)$$

Then, the weak form for the continuous asymptotic problem is, find  $p \in L^2(0, T, H^1(\mathcal{B}))$  such that:

$$orall \psi \in \mathsf{L}^2(\mathsf{0},\mathsf{T},\mathsf{H}^1(\mathcal{B})), \quad \mathsf{a}(\mathsf{p},\psi) = \mathsf{b}(\psi)$$

Lax-Milgram theorem can be used to prove the existence and unicity of a solution.

## Discrete weak form (Galerkin method)

- Let P<sup>1</sup><sub>h</sub>(B) be a the subspace of H<sup>1</sup>(B) of continuous functions which are piecewise linear over the subdivision of B.
- Let V<sub>h,k</sub> = ℙ<sup>0</sup><sub>k</sub>(0, T, ℙ<sup>1</sup><sub>h</sub>(B)) be the set of piecewise constant functions over the subdivision of [0, T] with values in ℙ<sup>1</sup><sub>h</sub>(B).

• Let us take 
$${\it K}_q^{(\sigma)}=0$$
 when  $q<0.$  For  $p,\psi\in V_{h,k}$ , let us denote:

$$\tilde{a}(p,\psi) = \int_{\mathcal{B}} k \sum_{q=0}^{Q-1} \sum_{\tilde{q}=0}^{Q-1} (K_{q-\tilde{q}} - K_{q-\tilde{q}-1}) \frac{\partial p}{\partial x} (\cdot, \frac{t_{\tilde{q}} + t_{\tilde{q}+1}}{2}) \frac{\partial \psi}{\partial x} (\cdot, \frac{t_{q} + t_{q+1}}{2})$$

• Let 
$$p_{h,k} \in \mathbb{V}_{h,k}$$
 such that  $p_{h,k}(X_s^{(e_j)}, \frac{t_q+t_{q+1}}{2}) = P_{s,q}^{(e_j)}$ .  
Then  $p_{h,k}$  is a solution to:

$$\forall \psi \in V_{h,k}, \quad \tilde{a}(p_{h,k},\psi) = \tilde{b}(\psi)$$

where  $\tilde{b}$  is a good approximation of b. Besides  $\|\tilde{a} - a\| \leq \theta(k)$ .

## Stability condition

A sufficient condition for existence and uniqueness for the discrete solution is the continuity and coercivity of the discrete form, uniformly when  $(h, k) \rightarrow (0, 0)$ .

Let  $\alpha_T$  be coercivity constant of *a*.

Here are two sufficient criterions:

- If  $\theta(k) < \mu < \alpha_T$ , then  $\tilde{a}$  is  $\alpha_T \mu$ -coercive.
- If there exists  $C, E, T_m \in \mathbb{R}^{+*}$  and  $(K_q^{(\sigma)})_{q \in \mathbb{Z}}$  such that:

• 
$$0 \le K_q^{(\sigma)} \le C$$
 if  $q \ge 0$ ,  
•  $K_{q+1}^{(\sigma)} - 2K_q^{(\sigma)} + K_{q-1}^{(\sigma)} \ge 0$  if  $q \ge 1$ ,  
•  $E \le \frac{K_{q+1}^{(\sigma)} - 2K_q^{(\sigma)} + K_{q-1}^{(\sigma)}}{k^2}$  if  $T_m \le qk \le 2T_m$ .

then, for  $k < \min\{T_m, T\}$ ,  $\tilde{a}$  is  $\frac{\tilde{C}}{T^2}$ -coercive, with  $\tilde{C}$  independent of T, h, k.

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#### Error estimate

According to Céa's lemma:

$$\|p_{h,k} - P\|_{L^{2}(0,T,H^{1}(\mathcal{B}))} \leq \frac{C}{\alpha_{T}} \left[ \inf_{\psi \in V_{h,k}} \|P - \psi\|_{L^{2}(0,T,H^{1}(\mathcal{B}))} + \frac{\theta(k)}{\alpha_{T} - \theta(k)} \|P\|_{L^{2}(0,T,H^{1}(\mathcal{B}))} + \|b - \tilde{b}\| \right]$$

If  $\Psi_I\in H^2_{00}(0,\mathcal{T})$  and  $f\in H^2_{00}(0,\mathcal{T},H^2_{dc}(\mathcal{B}))$ , then:

$$\|p_{h,k}-P\|_{L^2(0,T,H^1(\mathcal{B}))} \leq \frac{C}{\alpha_T - \theta(k)}(\theta(k) + h + k)$$

If we replace P by its interpolant of  $P_{h,k}$ , and if P is  $C^4$ :

$$\|p_{h,k} - P_{h,k}\|_{L^2(0,T,H^1(\mathcal{B}))} \leq \frac{C}{\alpha_T - \theta(k)}(\theta(k) + h^2 + k^2\log(T/K))$$

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### Test case

We built two test cases such that:

- The kernel for the cross-section is known (disk).
- One with a smooth pressure which vanishes and initial time and the other one such that is nonzero at initial time.
- $\Psi_{\ell}, f^{(e_i)}$  are smooth.

We used the scheme with:

- the exact kernel  $K_q^{(\sigma)} = rac{1}{k} \int_{t_q}^{t_{q+1}} K^{(\sigma)}(t) \mathrm{d}t.$
- $\bullet$  a numerical approximation obtained with finite  $\mathbb{P}^2\text{-elements}$  and BDF2 integrator in the cross-section
- the same numerical approximation, corrected with an asympotic expansion of K<sup>(σ)</sup> for small times.
- (See Éric Canon's talk for the details)

#### Numerical order

## Numerical order



two others are set by default to  $h = 2^{-10}, k = 0.1 \cdot 2^{-14}, H = \pi 2^{-10}$ .

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## Numerical order

		Numerical ap-	Corrected ap-	Exact
		proximation	proximation	
	h	2	2	2
$\beta = 0, P(\cdot, 0) \neq 0$	k	0.5	$\sim 1.4$	$\frac{3}{2}$
$\beta = 1, P(\cdot, 0) = 0$	k	$\sim 1.6$	$\sim 1.8$	2
$\beta = 0, P(\cdot, 0) \neq 0$	Н	1	$\sim 1.6$	
$\beta = 1, P(\cdot, 0) = 0$	Η	$\sim 1.7$	$\sim 1.7$	

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## Test-case for the comparison with full Navier-Stokes equation

$$O_{2}(1 + \cos \frac{\pi}{4}, \frac{3}{2}, 0) = \begin{cases} M \in \mathbb{R}^{3} | \exists i, O \in e_{i}, OM \perp e_{i}, \|OM\| < \varepsilon \}. \\ \{M \in \mathbb{R}^{3} | \exists i, O \in e_{i}, OM \perp e_{i}, \|OM\| < \varepsilon \}. \\ \text{Let us take the following boundary conditions:} \end{cases}$$

$$O_{5}(1 + \cos \frac{\pi}{4}, \sin \frac{\pi}{4}, 0) = 0 \text{ and } v(M, t) \text{ colinear to } e_{1} \text{ at the beginning } O_{1} \text{ of } e_{1}.$$

$$v(M, t) = -\frac{e_{2}}{|e_{2}|}v_{0}\sin(\varepsilon^{-2}40t)(1 - 4\varepsilon^{-2}\|O_{2}M\|^{2}) \text{ at the beginning } O_{2} \text{ of } e_{2}. \text{ The flux through this tube is then } \frac{1}{8}\pi v_{0}\varepsilon^{2}\sin(\varepsilon^{-2}40t);$$

$$v(M, t) = 2\frac{e_{3}}{|e_{3}|}v_{0}\sin(\varepsilon^{-2}40t)(1 - 4\varepsilon^{-2}\|O_{3}M\|^{2}) \text{ at the beginning } O_{3} \text{ of } e_{3}. \text{ The flux through this tube is then } \frac{\pi}{4}v_{0}\varepsilon^{2}\sin(\varepsilon^{-2}40t);$$

$$v = 0 \text{ on the rest of the boundary.}$$

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# Comparison between Navier-Stokes and the asymptotic model



Comparison between the asymptotic model (dashed lines) and the Navier-Stokes numerical solution (blue lines) for the multiply connected geometry when  $T = 0.0875\varepsilon^2$ ,  $\varepsilon = 0.1$ . On the left, the pressure along tubes. On the right, the velocity magnitude across the middle of the six tubes with respect to the distance to the axis of the tube.

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## Comparison between the 3D Navier-Stokes numerical solution and the asymptotic model. $T = 0.875\varepsilon^2$ .

 $p^{\epsilon}, P$  is the pressure on the graph for the NS numerical solution on the graph and for the asymptotic model.

 $q^{\varepsilon}$  is the orthogonal projection of  $p^{\varepsilon}$  on functions affine on each edge.  $\Phi_j^{\varepsilon}, \Phi_j$  is the flux accross the *j*-th tube according to Navier-Stokes numerical solution and the asymptotic model,

ε	0.2	0.1	0.05	0.025			
$\frac{\ P - p^{\varepsilon}\ _{L^{2}(0,T,H^{1}(\mathcal{B}))}}{\ p^{\varepsilon}\ _{L^{2}(0,T,H^{1}(\mathcal{B}))}}$	0.144626	0.103521	0.080028	0.062730			
$\frac{\ P-q^{\varepsilon}\ _{L^{2}(0,T,H^{1}(\mathcal{B}))}}{\ q^{\varepsilon}\ _{L^{2}(0,T,H^{1}(\mathcal{B}))}}$	0.036639	0.021016	0.031650	0.028022			
	0.035878	0.030196	0.056603	0.053661			
$\left\  \left( \Phi_j - \Phi_j^{\varepsilon} \right)_j \right\ _{L^2(\{1,\ldots,l\})}$	$M$ $\times$ [0, $T$ ])						
$\left\  (\Phi_j^{\varepsilon})_j \right\ _{L^2(\{1,\dots,M\}}$	$\times [0,T])$						
Remark: The Navier-Stokes simulation accuracy decreases when $arepsilon  o 0$							
because we were limited by computationnal cost.							
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## Two-dimensionnal case



23 / 26

2

## Comparison between the 2D Navier-Stokes and the asymptotic model



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## Conclusion

We got:

- Fast approximation of the asymptotic model.
- Good agreement with full Navier-Stokes equations.

Next talk by Éric Canon: Accurate approximation of the kernel K.

Thank you for your attention!

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Canon, Chardard, Panasenko, Stikoniene

Numerics for a fluid on a graph

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Galerkin finite element methods for parabolic problems, volume 25 of Springer Series in Computational Mathematics. Springer-Verlag, Berlin, second edition, 2006. x

#### Test case

We consider the case of a single tube (M = 1) of length 1 with two extremities  $O_1 = (\hat{0}, 0), O_2 = (\hat{0}, 1)$   $(N_1 = N = 2)$ . Let the cross-section of the tube be  $\sigma = \{x \in \mathbb{R}^2; \|x\|_2 < 1, \}$ . Let us take  $P((\hat{0}, x_3^{(e)}), t) = p(x_3^{(e)}, t) = \exp\left((1 - t)x_3^{(e)} - \frac{\beta}{t}\right)$  where  $\beta \in \{0, 1\}$ . When  $\beta = 1$ , P and all its time derivatives are zero when  $t \to 0$ .

Then, the flow at the left extremity  $O_1$  of the pipe is given by:

$$\Psi_1(t) = -\int_0^t \kappa^{(\sigma)}(s)(1-(t-s))\exp\left(-rac{eta}{t-s}
ight)\mathrm{d}s.$$

At the right extremity  $O_2$  of the pipe, it is given by:

$$\Psi_2(t) = -\int_0^t \kappa^{(\sigma)}(s)(1-(t-s))\exp\left(1-\frac{\beta}{t-s}\right)\mathrm{d}s.$$

The force applied along the pipe is:

$$F((\hat{0}, x_3^{(e)}), t) = -\int_0^t \mathcal{K}^{(\sigma)}(s)(1 - (t - s))^2 \exp\left(\left(1 - (t - s)\right) x_3^{(e)} - \frac{\beta}{t - s}\right) ds_{3, c}$$

Canon, Chardard, Panasenko, Stikoniene

Numerics for a fluid on a graph