



Observability for non-autonomous systems

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$$\dot{x}(t) = A(t)x(t), y(t) = C(t)x(t), t > 0, x(0) = x_0 \in X$$

Example: $A(t)$ strongly ellip. Diff. op. of L^p

$$C(t) = 1_{\Omega(t)} \text{ Mult. op.}$$

Question: If we sample $y(t)$ at time $E \subset [0, T]$ Can estimate $x(T)$

Final-state Obs.

$$\|x(T)\|_X \lesssim \int_E \|y(t)\|_Y dt$$

$A(t): \underline{D(A)} \rightarrow X, X$ B-Space

$C(t) \in \mathcal{L}(X, Y), Y$ B-Space

"Solution operator" for the CP

Evo Fam. $U(t, 0)$

$$U(\cdot, 0)_X := x(\cdot) \in L^1([0, T], D) \cap W^{1,1}([0, T], X)$$

Suff. Cond. for Obs.

- Exp. boundedness
- $(C(t))$ bounded fam.

$$\|U(t, 0)_X\| \leq \underbrace{\|(I - P_\lambda)U(t, 0)_X\|}_{\sim e^{-\lambda(t-s)} \|U(s, 0)_X\|} + \underbrace{\|P_\lambda U(t, 0)_X\|}_{\sim \|C(t)U(t, 0)_X\|}$$

• dissipation • uncertainty

Interp. $\lesssim \|U(s, 0)_X\|^\theta \|C(t)U(t, 0)_X\|^{1-\theta}$

$$\|U(\ell_m, 0)_X\| \lesssim \varepsilon \|U(\ell_{m+1}, 0)_X\|^\theta + \varepsilon^{\frac{\theta}{1-\theta}} \int_{\ell_m}^{\ell_{m+1}} \|C(t)U(t, 0)_X\| dt$$

$$\varepsilon^{\frac{\theta}{1-\theta}} \|U(\ell_m, 0)_X\| - \varepsilon^{\frac{1}{1-\theta}} \|U(\ell_{m+1}, 0)_X\| \lesssim \int_{\ell_{m+1}}^{\ell_m} \|C(t)U(t, 0)_X\| dt$$

II Application to Diff. Ops. Gld.

Op. $A(t)u := \mathcal{F}^{-1}(a(t, \cdot)\mathcal{F}u) = \sum_{|\alpha|_1 \leq m} a_\alpha(t)(-i)^\alpha \partial^\alpha u$

Evo. $U(t, s)u := \mathcal{F}^{-1}\left(e^{-\int_s^t a(\tau, \cdot) d\tau} \mathcal{F}u\right)$

Heat-Kernel Estimates \Rightarrow

Sufficient Cond. for

- Dissipation \leftarrow Kershner Est.
- Uncertainty \leftarrow Logarithmic - Sereda

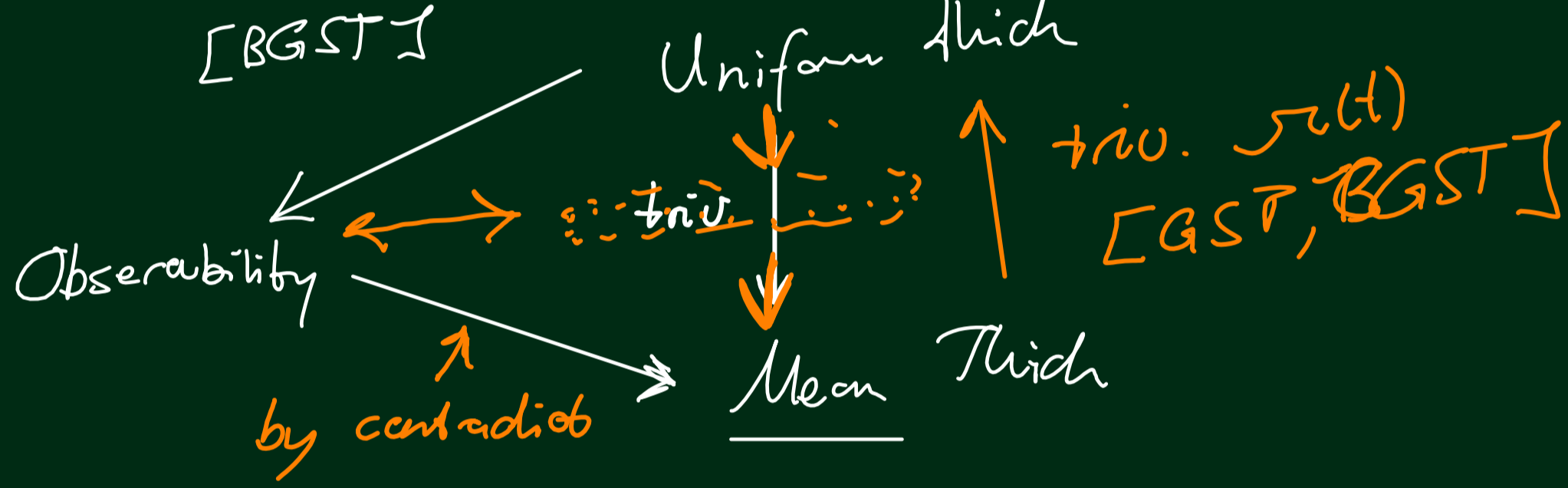
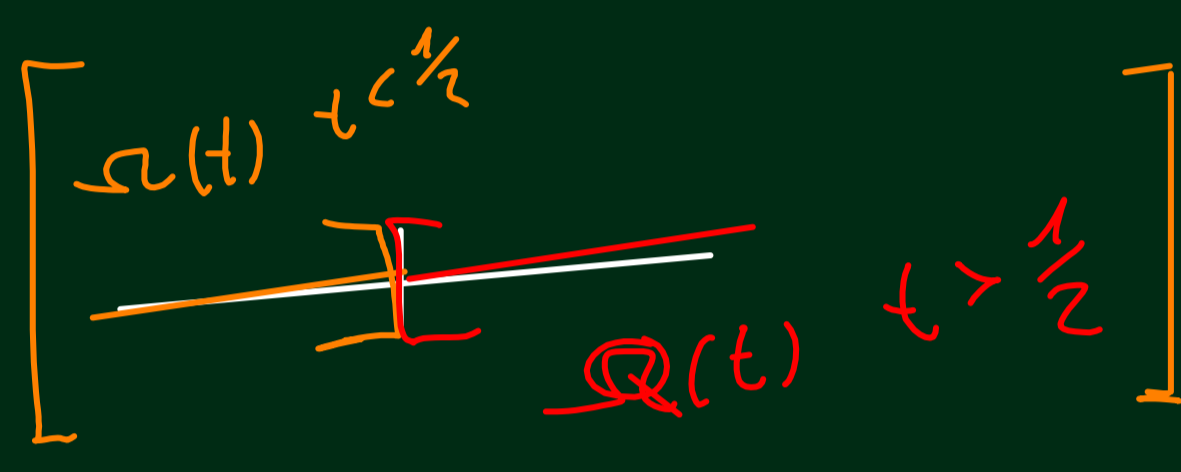
\downarrow
 $(\Omega(t)) \quad C(t) = \mathbb{1}_{\Omega(t)}$

- measurable
- "thickness"

(1) $\Omega(t)$ unif. thick

$\forall t \quad |\Omega(t) \cap Q^d| \gtrsim |Q^d|$

(2) mean thick $\forall Q \quad \int_{\Omega(t) \cap Q} 1 \gtrsim |Q^d|$



- Georg Michel
- Parzy
- Lunardi

References (Links 2 go in zoom-chat)

[BGST]

arXiv:2005.14503 [pdf, ps, other] [math.FA](#) [math.AP](#) [math.OC](#)
Observability and null-controllability for parabolic equations in L_p -spaces
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[GST]

arXiv:1905.10285 [pdf, ps, other] [math.FA](#) [math.AP](#) [math.OC](#) [doi](#) 10.1137/19M1266769
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[BEP-S]

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Geometric conditions for the null-controllability of hypoelliptic quadratic parabolic equations with moving control supports
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[BGabST] In preparation...