

# On a construction of quaternionic and octonionic Riemann surfaces

(extract from [2]) by G. GENTILI, J. PREZELJ AND F. VLACCI

## Introduction

Let  $\mathbb{K}$  denote either the division algebra of quaternions  $\mathbb{H}$  or that of octonions  $\mathbb{O}$ , and let  $\mathbb{S} \subset \mathbb{K}$  be the 2-sphere or, respectively, the 6-sphere of imaginary units, i.e. the sets of  $I \in \mathbb{K}$  such that  $I^2 = -1$ . If  $I \in \mathbb{K}$  we define the *slice*  $\mathbb{C}_I := \mathbb{R} + I\mathbb{R}$  and say that a domain  $\Omega \subset \mathbb{K}$  is a *slice domain* if  $\Omega \cap \mathbb{R} \neq \emptyset$  and  $\Omega_I := \Omega \cap \mathbb{C}_I$  is a domain in  $\mathbb{C}_I$  for any  $I \in \mathbb{S}$ .

Let  $\Omega \subseteq \mathbb{K}$  be a slice domain and let  $f : \Omega \rightarrow \mathbb{K}$  be a function. If, for an imaginary unit  $I$  of  $\mathbb{K}$ , the restriction  $f_I := f|_{\Omega_I}$  has continuous partial derivatives and

$$\bar{\partial}_I f(x + yI) := \frac{1}{2} \left( \frac{\partial}{\partial x} + I \frac{\partial}{\partial y} \right) f_I(x + yI) \equiv 0. \quad (1)$$

then  $f_I$  is called *holomorphic*. If  $f_I$  is holomorphic for all imaginary units of  $\mathbb{K}$ , then the function  $f$  is called *slice regular*.

We refer the interested reader to the monograph [1] for an introduction to the main properties of slice regular functions in the quaternionic setting.

## Main results

As customary, a differentiable map will be called an *immersion* if its differential is injective at all points of the domain of definition.

Let  $n, N$  be natural numbers with  $N \geq n$  and let  $\Omega$  be domain in  $\mathbb{R}^n$ . An at least  $C^1$  immersion  $f : \Omega \rightarrow \mathbb{R}^N$  will be called a *conformal or isothermal map* if the matrix of the differential of  $f$  is conformal, i.e., if it satisfies

$${}^t df(p)df(p) = k(p)I_n \quad (2)$$

for a (never vanishing and at least  $C^1$ ) function  $k : \Omega \rightarrow \mathbb{R}$

We specialize this definition for our purposes.

Let  $\Omega$  be a slice domain in  $\mathbb{H} \cong \mathbb{R}^4$  and let  $N \geq 4$  be a natural number. Let  $f : \Omega \rightarrow \mathbb{R}^N$  be an at least  $C^1$  immersion. If, for any  $I \in \mathbb{S}$ ,  $df|_{\mathbb{C}_I}$  and  $df|_{\mathbb{C}_I^\perp}$  satisfy (2), then  $f$  will be called a *slice conformal or slice isothermal immersion*.

Notice that in general slice conformality does not imply conformality.

If  $f$  is an injective slice conformal immersion, then it will be called *slice conformal or slice isothermal parameterization* and  $f(\Omega)$  in  $\mathbb{R}^N$  will be called a (*parameterized*) *Riemann 4-manifold* of  $\mathbb{R}^N$ . In case  $f : \Omega \rightarrow \mathbb{R}^N$  itself is a conformal map, then the parameterized 4-manifold  $f(\Omega)$  in  $\mathbb{R}^N$  will be called a *special (parameterized) Riemann 4-manifold* of  $\mathbb{R}^N$ .

Let  $\Omega \subseteq \mathbb{H}$  be a slice domain; consider  $F : \Omega \rightarrow \mathbb{H}^2 \cong \mathbb{R}^8$  where  $F(q) = (f(q), g(q))$  with  $f, g : \Omega \rightarrow \mathbb{H}$  slice regular functions. If  $F$  is an immersion, then  $F$  will be called a *slice regular curve* (in  $\mathbb{H}^2$ ). Furthermore, if  $F$  is injective, then  $F(\Omega)$  is a parameterized Riemann 4-manifold in  $\mathbb{H}^2$ .

If  $f : \Omega \rightarrow \mathbb{H}$  is any slice regular function, the slice regular curve  $F : \Omega \rightarrow \mathbb{H}^2$   $F(q) := (q, f(q))$  is a slice conformal parameterization and the graph of  $f$ , i.e.  $\Gamma(f) = \{(q, f(q)) : q \in \Omega\} \subseteq \mathbb{H} \times \mathbb{H}$  is a parameterized Riemann 4-manifold.

## The Riemann 4-sphere

Let  $f : \mathbb{R}^4 \cong \mathbb{H} \rightarrow \mathbb{H} \times \mathbb{R} \cong \mathbb{R}^5$  be

$$f(x + yI) = \left( \frac{2(x + yI)}{1 + x^2 + y^2}, \frac{-1 + x^2 + y^2}{1 + x^2 + y^2} \right).$$

Then  $df(x + yI)|_{\mathbb{C}_I} =$

$$= \frac{2}{(1 + x^2 + y^2)^2} \begin{bmatrix} 1 - x^2 + y^2 & -2xy \\ -2xy & 1 + x^2 - y^2 \\ 0 & 0 \\ 0 & 0 \\ 2x & 2y \end{bmatrix}$$

$df(x + yI)|_{\mathbb{C}_I^\perp} =$

$$= \frac{2}{(1 + x^2 + y^2)^2} \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 1 + x^2 + y^2 & 0 \\ 0 & 1 + x^2 + y^2 \\ 0 & 0 \end{bmatrix}$$

## The Helicoidal 4-manifold

Consider  $g : \mathbb{R}^4 \cong \mathbb{H} \rightarrow \mathbb{H} \times \Im\mathbb{H} \cong \mathbb{R}^7$  with  $g(x + yI) =$

$$= (\sinh x \cos y + I \sinh x \sin y, yI) =$$

$$= (sh(x)c(y) + Ish(x)s(y), yI),$$

then

$$dg(x + yI)|_{\mathbb{C}_I} = \begin{bmatrix} ch(x)c(y) & -sh(x)s(y) \\ ch(x)s(y) & sh(x)c(y) \\ 0 & 0 \\ 0 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$dg(x + yI)|_{\mathbb{C}_I^\perp} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ \frac{sh(x)s(y)}{y} & 0 \\ 0 & \frac{sh(x)c(y)}{y} \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

If  $\mathbb{H}^+ = \{q \in \mathbb{H} : \Re q > 0\}$  put  $\mathcal{E}^+ = g(\mathbb{H}^+)$ , and  $E(x + yI) := (\exp(x + yI), yI) = (\exp x \cos y + I \exp x \sin y, yI)$  defines an immersion and a diffeomorphism between  $\mathbb{H}$  and  $\mathcal{E}^+$  such that  $\pi \circ E = \exp$ ; then  $L : \mathcal{E}^+ \subset \mathbb{H} \times \Im\mathbb{H} \rightarrow \mathbb{H}$   $L(q, p) = \log |q| + p$  is the  $\mathcal{E}^+$ -logarithm. Indeed, if  $(q, p) \in \mathcal{E}^+$ , then  $q = |q| \exp p$  and so  $E \circ L$  and  $L \circ E$  are the identity.

## References

- [1] G. Gentili, C. Stoppato, D. C. Struppa, REGULAR FUNCTIONS OF A QUATERNIONIC VARIABLE, Springer Monographs in Mathematics, Springer, Berlin-Heidelberg, 2013
- [2] G. Gentili, J. Prezelj, F. Vlacci, *Slice conformality: Riemann manifolds and logarithm on quaternions and octonions* in arXiv.org > math > math.CV