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Compactness properties of operator of translation along trajectories in evolution equations

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Aims ●000			

Let us consider following autonomous wave equation:

$$u_{tt} + \alpha u_t = \Delta u - V(x)u + f(t, x, u), t > 0, x \in \mathbb{R}^N,$$
(1)

where  $\alpha \geq 0$  is a damping coefficient and V is the so called Kato-Rellich potential, i. e.  $V = V_{\infty} - V_0$ ,  $V_{\infty} \in L^{\infty}(\mathbb{R}^N)$ ,  $V_0 \in L^p(\mathbb{R}^N)$ , 2 . Ingeneral, the nonlinear forcing term <math>f is continuous and locally Lipschitz (currently we work yet by global Lipschitz condition) with respect to the third variable and T-periodic in time, i.e. f(t + T, x, u) = f(t, x, u). The two cases must be considered separately: the resonant and non-resonant ones. In the resonant case, that is when the kernel space of the linearization of the  $-\Delta + V(x) + f(t, x, \cdot)$  is nontrivial, i. e.

$$\mathcal{N} := \operatorname{Ker}\left(-\Delta + V\right) \neq \{0\}.$$
(2)

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We introduce so-called Landesman-Lazer type conditions, which mean that

$$\int_{0}^{T} \left( \int_{\{\phi>0\}} \check{f}_{+}(t,x)\phi(x) \ dx + \int_{\{\phi<0\}} \hat{f}_{-}(t,x)\phi(x) \ dx \right) \ dt > 0, \quad (3)$$

for any  $\phi \in \mathcal{N} \setminus \{0\}$ , where  $\check{f}_+(t,x) := \liminf_{s \to +\infty} f(t,x,s)$  and  $\hat{f}_-(t,x) := \limsup_{s \to -\infty} f(t,x,s)$  or

$$\int_{0}^{T} \left( \int_{\{\phi>0\}} \hat{f}_{+}(t,x)\phi(x) \ dx + \int_{\{\phi<0\}} \check{f}_{-}(t,x)\phi(x) \ dx \right) \ dt < 0,$$
 (4)

for any  $\phi \in \mathcal{N} \setminus \{0\}$ , where  $\hat{f}_+(t,x) := \limsup_{s \to +\infty} f(t,x,s)$  and  $\check{f}_-(t,x) := \liminf_{s \to -\infty} f(t,x,s)$ . It is noteworthy that the conditions of that type can be verified without the

explicit knowledge of  $\mathcal{N}$  (see Remark 1.3 in [5]).

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We are now in point to state our first theorem

## Theorem 1

Suppose that we have problem (1) with assumptions about V(x) and f(t, x, u) as mentioned above and additionally we request that f is bounded by square integrable function, i. e. there exists  $m \in L^2(\mathbb{R}^N)$  such that for all  $t \in [0, \infty)$ ,  $u \in \mathbb{R}$  and almost every  $x \in \mathbb{R}^N$ 

 $|f(t, x, u)| \le m(x).$ 

Moreover, we require that resonance condition (2) holds as well as one Landesman-Lazer conditions (3), (4). Next we assume that

$$a_{\infty} := \lim_{R \to +\infty} \operatorname{essinf}_{|x| \ge R} \, V_{\infty}(x)$$

is a positive number and  $0 \in \sigma_p(-\Delta + V(x))$ . Then there exists *T*-periodic solution of (1).

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The second case concerning situation when there are no resonance, which means that  $-\Delta + V(x) + f(t, x, \cdot)$  at zero and infinity has trivial kernels. We shall use the following linearizations of f

$$\lim_{u \to 0} \frac{f(t, x, u)}{u} = \alpha(t, x), \qquad \lim_{|u| \to \infty} \frac{f(t, x, u)}{u} = \omega(t, x), \tag{5}$$

for all  $x\in\mathbb{R}^N$  and  $t\ge 0$ , where  $\alpha(t,.),\ \omega(t,.)$  are Kato-Rellich potentials. We work under the assumption that

$$\operatorname{Ker}\left(-\Delta + V - \widehat{\omega}\right) = \{0\} \quad \text{and} \quad \operatorname{Ker}\left(-\Delta + V - \widehat{\alpha}\right) = \{0\}, \qquad (6)$$

where

$$\widehat{\alpha}(x) := \frac{1}{T} \int_0^T \alpha(t,x) \ dt, \ \widehat{\omega}(x) := \frac{1}{T} \int_0^T \omega(t,x) \ dt$$

Now we formulate theorem concerning nonresonance case.

## Theorem 2

Suppose that we have problem (1) with assumptions about V(x) and f(t, x, u) as mentioned above. Moreover, we require that nonresonance condition (6) holds and linearizations of right-hand-side of (1) are topologically different, i. e. numbers of the negative eigenvalues (counted with multiplicities) of  $-\Delta + V - \hat{\alpha}$  and  $-\Delta + V - \hat{\omega}$  are different modulo 2. Then there exists *T*-periodic solution of (1).

	Evolutionary problem				
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The hyperbolic equation (1) can be rewritten as the system on space  ${\bf X}=H^1(\mathbb{R}^N)\times L^2(\mathbb{R}^N)$ 

$$\begin{cases} u_t = v - \delta u\\ v_t = -(-\Delta + V(x))u - (\alpha - \delta)(v - \delta u) + f(t, x, u) \end{cases}$$
(7)

with  $\delta \ge 0$  (see section 2.1 in [8]). We equip space  $\mathbf{X}$  with usual scalar product  $(., .)_{\mathbf{X}} := (., .)_{H^1} + (., .)_{L^2}$ .

Evolutionary problem		
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Subsequently we transform formula above into first order differential equation

$$(u_t, v_t) = -(\mathbf{A}_0 + \mathbf{V})(u, v) + \mathbf{F}(t, u, v), \ t > 0,$$
(8)

where  $\mathbf{A}_0: D(\mathbf{A}_0) \subset \mathbf{X} \to \mathbf{X}$ , is defined by  $D(\mathbf{A}_0) = H^2(\mathbb{R}^N) \times H^1(\mathbb{R}^N)$  and

$$\mathbf{A}_0(u,v) := \left(\delta u - v, -\Delta u + (\alpha - \delta)v + (\delta^2 - \alpha\delta)u\right),$$

and  $\mathbf{V}:\mathbf{X}\rightarrow\mathbf{X}$  by

$$\mathbf{V}(u,v) = (0, V(x)u).$$

The mapping  $\mathbf{F}:[0,+\infty)\times \mathbf{X}\to \mathbf{X}$  is given by

$$\mathbf{F}(t, u, v) := (0, F(t, u))$$

with the Nemytskii operator  $F:[0,+\infty)\times H^1(\mathbb{R}^N)\to L^2(\mathbb{R}^N)$  given by [F(t,u)](x):=f(t,x,u(x)).

Evolutionary problem		
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It is may be shown, by use of the Lumer-Phillips theorem, that  $-(\mathbf{A}_0 + \mathbf{V})$  is the generator of  $C_0$ -semigroup of contractions  $\{\mathbf{S}_{-(\mathbf{A}_0 + \mathbf{V})}(t)\}_{t \ge 0}$ , which enables us to consider mild solutions of (8), i. e we say that function  $(u(.), v(.)) : [0, \tau] \to \mathbf{X}$  is a mild solution with initial condition  $(\bar{u}, \bar{v})$  if it satisfies following integral formula

$$(u(t), v(t)) = \mathbf{S}_{-(\mathbf{A}_0 + \mathbf{V})}(t)(\bar{u}, \bar{v}) + \int_0^t \mathbf{S}_{-(\mathbf{A}_0 + \mathbf{V})}(t-s)\mathbf{F}(s, u(s), v(s)) \, ds,$$
(9)

for any  $t \in [0, \tau]$ . Consequently, we say that  $u : [0, \tau] \to H^1(\mathbb{R}^N)$  is a mild solution of (1) if there exists  $v : [0, \tau] \to L^2(\mathbb{R}^N)$  such that (u, v) is a mild solution of (8). In particular, under reasonable assumptions on f, we have the Poincaré operator of translation along trajectories  $\Phi_T : \mathbf{X} \to \mathbf{X}$  associated with (8), defined by

$$\mathbf{\Phi}_T(\bar{u}, \bar{v}) := (u(T), v(T)),$$

where  $(u, v) : [0, T] \to \mathbf{X}$  is the mild solution of (8) with the initial condition  $(u(0), v(0)) = (\bar{u}, \bar{v})$  (the existence and uniqueness come from standard  $C_0$ -semigroup theory, see e.g. [11] or [3]). Observe that if  $(\bar{u}, \bar{v}) \in \mathbf{X}$  is a fixed point of  $\Phi_T$ , i.e.  $\Phi_T(\bar{u}, \bar{v}) = (\bar{u}, \bar{v})$ , then the mild solution of (8) is *T*-periodic. Therefore we search for fixed points of  $\Phi_T$ .

	Index theory		

Let  $(E, \|.\|)$  be a Banach space. We say that  $G : E \to E$  is *ultimately compact* if for any bounded  $D \subset E$  such that

 $D \subset \overline{\operatorname{conv}}(G(D)),$ 

then D is relatively compact in E. Observe that any compact map is ultimately compact. We recall that conv(D) means convex hull of set D and  $\overline{conv}(D)$ means convex closed hull of D (we consider closure in space E). There are possible slightly general definitions, for instance see section 2 in [6]. We are in a position to introduce index theory for ultimately compact sets due to Sadovskii (see Section 3.5.6 in [1]). It is an improvement of index for so-called condensing operators due to Nussbaum and Sadovskii (see Chapter 4 in [10]). One can show that index for ultimately compact operator possesses standard preperties (existence, additivity, homotopy invariance and normalization). Moreover, it is also true, that if G is a compact map, then index for ultimately compact operators coincides with Leray-Schauder index. Further we will denote index of ultimate compact map G with respect to open set  $U \subset E$  by  $Ind_{uc}(G, U)$ .

	Tail estimates ●0000	

According to what was said before we need to prove that Poincaré operator of translation along trajectories is ultimately compact. One of techniques is based on the so-called tail estimates of solutions, for instance estimation of sequences

$$\int_{\{|x|\ge n\}} |u(x,t)|^2 \, dx,$$

where  $u:[0,\infty)\to H^1(\mathbb{R}^N)$  is a solution of parabolic equation

$$u_t = \Delta u - V(x)u + f(t, x, u), \ t > 0, \ x \in \mathbb{R}^N.$$
 (10)

The tail estimate method was originated for parabolic equations by Wang in [13]. A tail estimates enabling applications of Conley index to parabolic equation and the associated semiflow on  $H^1(\mathbb{R}^N)$  was shown in [12] and adapted in [5]. We shall follow ideas from [6] and [7] for parabolic problems (10) and from [8] for hyperbolic problems.

	Tail estimates	
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Assume now that, for all  $t \ge 0$ ,  $x \in \mathbb{R}^N$  and  $u_1, u_2 \in \mathbb{R}$ ,

$$|f(t, x, u_1) - f(t, x, u_2)| \le l(x)|u_1 - u_2|$$

where l is a Rellich-Kato type function. Let  $u_1, u_2$  be two solution of (8). Then  $u := u_1 - u_2$  and  $v := \delta u + \dot{u}$  satisfy

$$\dot{u} = \Delta u - ((\alpha - \delta)\delta - V)u - (\alpha - \delta)u + F(t, u_1) - F(t, u_2)$$

Furthermore,  $\phi: [0,\infty) \to \mathbb{R}$  be smooth function such that  $\phi([0,\infty)) \subset [0,1]$ , for any  $s \in [0,1]$   $\phi(s) = 0$  and for any  $s \in [2,\infty)$   $\phi(s) = 1$ . Then for any  $k \in \mathbb{N}_{\geq 1}$  we put  $\phi_k: \mathbb{R}^N \to \mathbb{R}$ ,  $\phi_k(x) := \phi(|x|^2/k^2)$ , where |.| stands for norm in  $\mathbb{R}^N$ . By the regularity theory (see [2])

$$\frac{1}{2}\frac{d}{dt}(v,v\phi_k)_0 = (\dot{v},v\phi_k)_0 = (\Delta u,v\phi_k)_0 + (((\alpha-\delta)\delta-V)u,v\phi_k)_0 + -(\alpha-\delta)(v,v\phi_k)_0 + (F(t,u_1)-F(t,u_2),v\phi_k)_0 = I_1 + I_2 + I_3$$

with

$$I_{1} = (\Delta u, v\phi_{k})_{0}, \quad I_{2} = (((\alpha - \delta)\delta - V)u, v\phi_{k})_{0},$$
  

$$I_{3} = -(\alpha - \delta)(v, v\phi_{k})_{0} + (F(t, u_{1}) - F(t, u_{2}), v\phi_{k})_{0}.$$

			Tail estimates		Resonant case
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Clearly

$$I_1 \leq -\frac{1}{2}\frac{d}{dt}(\nabla u, \nabla u\phi_k)_0 - \delta(\nabla u, \nabla u\phi_k)_0 + c_k^{(1)}$$

where  $c_k^{(1)} \to 0^+$  as  $k \to +\infty.$  Further we have

$$I_{2} = (((\alpha - \delta)\delta - a_{\infty})u, \dot{u}\phi_{k} + \delta u\phi_{k})_{0} + ((a_{\infty} - V)u, v\phi_{k})_{0}$$
  
$$= -\frac{1}{2}\frac{d}{dt}((a_{\infty} - (\alpha - \delta)\delta)u, u\phi_{k})_{0} - \delta((a_{\infty} - (\alpha - \delta)\delta)u, u\phi_{k})_{0} + ((a_{\infty} - V_{\infty})u, v\phi_{k})_{0} + (V_{0}u, v\phi_{k})_{0} \leq$$
  
$$\leq -\frac{1}{2}\frac{d}{dt}((a_{\infty} - (\alpha - \delta)\delta)u, u\phi_{k})_{0} - \delta((a_{\infty} - (\alpha - \delta)\delta)u, u\phi_{k})_{0} + c_{k}^{(2)},$$

where

$$c_k^{(2)} = (V_0 u, v \phi_k)_0.$$

Clearly, by standard tail estimate techniques

$$c_k^{(2)} \to 0^+$$
 as  $k \to +\infty$ .

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	Tail estimates	
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Finally observe that, that for large k,

$$I_{3} = -(\alpha - \delta)(v, v\phi_{k})_{0} + (F(t, u_{1}) - F(t, u_{2}), v\phi_{k})_{0}$$

$$\leq -(\alpha - \delta)(v, v\phi_{k})_{0} + \operatorname{essup}_{|x| \geq k} l_{\infty}(x)(|u|, |v|\phi_{k})_{0} + (l_{0}|u|, |v|\phi_{k})_{0}$$

$$\leq -(\alpha - \delta)(v, v\phi_{k})_{0} + (\bar{l}_{\infty}/2) \varepsilon(v, v\phi_{0}) + (\varepsilon \bar{l}_{\infty}/2) (u, u\phi_{k})_{0} + c_{k}^{(3)}$$

with

$$\bar{l}_{\infty} = \lim_{R \to +\infty} \operatorname{essup}_{|x| \ge k} l_{\infty}(x)$$

 $c_k^{(3)} \to 0^+$  as  $k \to +\infty$ . Hence if we put  $D(t) := (\nabla u, \nabla u \phi_k)_0 + ((a_{\infty} - (\alpha - \delta)\delta)u, u\phi_k)_0 + (v, v\phi_k)_0$ 

then, by the above esitmates we get

$$\begin{split} \dot{D}(t) &\leq -2\delta D(t) - (\alpha - 2\delta)(v, v\phi_k)_0 + \bar{l}_\infty/2\varepsilon(v, v\phi_0) + \left(\varepsilon \bar{l}_\infty/2\right)(u, u\phi_k)_0 + c_k \\ \text{with } c_k \to 0^+ \text{ as } k \to +\infty. \text{ If we find } \varepsilon > 0 \text{ and } \delta > 0 \text{ such that} \end{split}$$

$$-\delta - (\alpha - 2\delta) + \frac{L}{2\varepsilon} < 0$$
 and  $\frac{\varepsilon L}{2(a_{\infty} - (\alpha - \delta)\delta)} - \delta < 0$  (11)

with  $L = \overline{l}_{\infty}$ , then we get  $\rho > 0$  such that

$$\dot{D}(t) \le -\rho D(t) + c_k,$$

	Tail estimates	
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Observe that, for any  $\delta \in (0, \alpha)$ ,

$$(\alpha - \delta)\delta \le (\alpha/2)^2$$

and that if we assume that

$$a_{\infty} > \left(\alpha/2\right)^2$$

and find  $\delta>0$  and  $\varepsilon>0$  such that

$$\delta < \alpha - \frac{L}{2\varepsilon} \quad \text{and} \quad \frac{\varepsilon L}{2(a_\infty - (\alpha/2)^2)} < \delta$$

then these numbers satisfy (11). It can be shown that such numbers exists if

$$L/2 < \alpha^2 (a_\infty - (\alpha/2)^2).$$

Theorem 3 If  $a_{\infty}$ ,  $\bar{l}_{\infty}$  and  $\alpha$  satisfy

$$\bar{l}_{\infty} < 2\alpha^2 (a_{\infty} - (\alpha/2)^2),$$

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then the Poincaré operator  $\Phi_T: \mathbf{X} o \mathbf{X}$  is ultimately compact.

		Nonresonant case	
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Once having the ultimate property, we shall be able to perform fixed point index computations for  $\Phi_T$  using some geometric properties of the equation. The resonant and non-resonant cases are considered separately. We shall follow the ideas from [6] and [7].

In the non-resonant case we shall consider the following family of equations

$$(u_t, v_t) = -(\mathbf{A}_0 + \mathbf{V})(u, v) + \mathbf{F}(t/\varepsilon, u, v), \ t > 0,$$
(12)

where  $\varepsilon \in (0, 1]$ . First we shall show that the non-resonance conditions (6) imply the existence of r > 0 and R > 2r such that, for all  $\varepsilon \in (0, 1]$ , the equation (12) has no nontrivial  $\varepsilon T$ -periodic solution with

$$(u(0), v(0)) \in B_{\mathbf{X}}(0, 2r) \cup (\mathbf{X} \setminus B_{\mathbf{X}}(0, R)).$$

This will enable us to consider the translation along trajectories operator  $\Phi_T^{(\varepsilon)}$  for (12) and ask for the indices  $\operatorname{Ind}_{uc}(\Phi_T^{(\varepsilon)}, B_{\mathbf{X}}(0, r))$  and  $\operatorname{Ind}_{uc}(\Phi_T^{(\varepsilon)}, B_{\mathbf{X}}(0, R))$  where  $\operatorname{Ind}_{uc}$  denotes fixed point index for ultimately compact mappings. By the homotopy property (note that  $\Phi_T = \Phi_T^{(1)}$ )

$$\operatorname{Ind}_{uc}(\Phi_T, B_{\mathbf{X}}(0, r)) = \lim_{\varepsilon \to 0^+} \operatorname{Ind}_{uc}(\Phi_T^{(\varepsilon)}, B_{\mathbf{X}}(0, r))$$

and

$$\operatorname{Ind}_{uc}(\Phi_T, B_{\mathbf{X}}(0, R)) = \lim_{\varepsilon \to 0^+} \operatorname{Ind}_{uc}(\Phi_T^{(\varepsilon)}, B_{\mathbf{X}}(0, R)).$$

		Nonresonant case	
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Then the averaging principle (see e.g. [9] or [4]) will be used to show that, for  $U = B_{\mathbf{X}}(0, r)$  and  $U = B_{\mathbf{X}}(0, R)$ , there exists  $\varepsilon_0 > 0$  such that, for all  $\varepsilon \in (0, \varepsilon_0]$ , one has

$$\operatorname{Ind}_{uc}(\mathbf{\Phi}_T^{(\varepsilon)}, U) = \operatorname{Ind}_{uc}(\widehat{\mathbf{\Phi}}_{\varepsilon T}, U)$$

where  $\widehat{\Phi}_t$ , t > 0, are the Poincaré operators associated with

$$u_{tt} + \alpha u_t = \Delta u - V(x)u + \hat{f}(x, u), \ t > 0, \ x \in \mathbb{R}^N,$$
(13)

that is with

$$(u_t, v_t) = -(\mathbf{A}_0 + \mathbf{V})(u, v) + \widehat{\mathbf{F}}(u, v), t > 0,$$
(14)

where  $\widehat{f}(x,u) := \frac{1}{T} \int_0^T f(t,x,u) dt$  and  $[\widehat{\mathbf{F}}(u,v)](x) := (0,\widehat{f}(x,u(x)))$ . Hence, to find the indices

 $\operatorname{Ind}_{uc}(\Phi_T, B_{\mathbf{X}}(0, r))$  and  $\operatorname{Ind}_{uc}(\Phi_T, B_{\mathbf{X}}(0, R))$ 

it sufficient to compute the fixed point index of  $\widehat{\Phi}_t$  for small t > 0.

		Nonresonant case	
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To get the fixed point index of  $\widehat{\Phi}_t$  we shall use the linearization method and the spectral properties of operators  $-\Delta + V - \widehat{\alpha}$  and  $-\Delta + V - \widehat{\omega}$ . Namely, we expect that there exists  $t_0 > 0$  such that, for all  $t \in (0, t_0]$ ,

 $\operatorname{Ind}_{uc}(\Phi_T, B_{\mathbf{X}}(0, r)) = (-1)^{m(0)}$  and  $\operatorname{Ind}_{uc}(\Phi_T, B_{\mathbf{X}}(0, R)) = (-1)^{m(\infty)}$ 

where m(0) is the number of negative eigenvalues of  $-\Delta + V - \hat{\alpha}$  (counted with their multiciplities) and  $m(\infty)$  is the number of negative eigenvalues of  $-\Delta + V - \hat{\omega}$ . Here we use the Weyl spectral theorem to see that the essential spectra of  $-\Delta + W_{\infty}$  and  $-\Delta + W_{\infty} + W_0$  coincide if  $W_{\infty} + W_0$  is a Kato-Rellich potential. Finally, by means of the additivity property of fixed point index, we shall arrive at

$$Ind_{uc}(\mathbf{\Phi}_T, B_{\mathbf{X}}(0, R) \setminus B_{\mathbf{X}}(0, r)) = (-1)^{m(\infty)} - (-1)^{m(0)}$$

i.e. the formula showing the assertion, i.e. if  $m(0) \neq m(\infty) \mod 2$ , then  $\operatorname{Ind}_{uc}(\Phi_T, B_{\mathbf{X}}(0, R) \setminus B_{\mathbf{X}}(0, r)) \neq 0$ , which implies the existence of *T*-periodic solution starting from  $B_{\mathbf{X}}(0, R) \setminus B_{\mathbf{X}}(0, r)$ .

		Resonant case
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If equation (1) is at resonance, that is  $\mathcal{N} = \ker(-\Delta + V) \neq \{0\}$ , then we shall consider the following parameterized equation

$$u_{tt} + \alpha u_t = \Delta u - V(x)u + \varepsilon f(t, x, u), \ t > 0, \ x \in \mathbb{R}^N$$
(15)

and the associated first order problem

$$(u_t, v_t) = -(\mathbf{A}_0 + \mathbf{V})(u, v) + \varepsilon \mathbf{F}(t, (u, v)), t > 0$$

with associated operator of translation  $\Phi_T^{(\varepsilon)}$ . Let  $P: L^2(\mathbb{R}^N) \to \mathcal{N}$  be the orthogonal projection onto  $\mathcal{N}$ . Observe that  $\mathcal{N} \subset H^1(\mathbb{R}^N)$  and, in view of the Riesz-Schauder theory,  $\dim \mathcal{N} < \infty$ . Then  $L^2(\mathbb{R}^N) = \mathcal{N} \oplus \mathcal{N}^{\perp}$  and consequently  $H^1(\mathbb{R}^N) = \mathcal{N} \oplus (\mathcal{N}^{\perp} \cap H^1(\mathbb{R}^N))$ . Subsequently we put  $\overline{F}(u) = \frac{1}{T} \int_0^T PF(t, u) \ dt$ . We expect that if  $U \subset \mathcal{N}$  is an open bounded set such that  $\overline{F}(\overline{u}) \neq 0$  for any  $\overline{u} \in \partial U$ , then for any r, R > 0 exists  $\varepsilon_0 \in (0, 1]$  such that for all  $\varepsilon \in (0, \varepsilon_0]$  we have

$$\operatorname{Ind}_{uc}\left(\Phi_{T}^{\varepsilon}, (U \oplus B_{r}) \times B(0, R)\right) = (-1)^{m(\infty) + \dim \mathcal{N}} \operatorname{Deg}_{B}(\bar{F}, U),$$

where  $B_r = \{u \in \mathcal{N}^{\perp} \cap H^1(\mathbb{R}^N) \mid ||u||_{H^1} < r\}$ , B(0, R) is an open ball in  $L^2(\mathbb{R}^N)$  centered in 0 with radius  $R, m(\infty)$  is a number of negative eigenvalues (counted with multiplicities) of  $-\Delta + V$  and  $\text{Deg}_B$  denotes topological Brouwer degree.

		Resonant case

Next step of our reasoning should be proving resonance version of continuation principle: if there exists  $R_0 > 0$  such that  $\text{Deg}_B(\bar{F}, B_N(0, R_0)) \neq 0$  $(B_N(0, R_0) = \{u \in \mathcal{N} \mid ||u||_{H^1} < R_0\})$  and for any  $\varepsilon \in (0, 1)$  there are not T-periodic solutions with  $||z(0)||_{\mathbf{X}} \geq R_0$  of (15), then equation

$$z_t = -(\mathbf{A}_0 + \mathbf{V})z + \mathbf{F}(t, z), \ t > 0$$
(16)

has a T-periodic solution. Hence a crucial point is to show that Brouwer degree associated with  $\bar{F}$  is nontrivial. We suppose that Landesman-Lazer conditions allow us to provide such result, and, in consequence, an existence of T-periodic solutions of equations in resonance.

		Resonant case

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