## The topological conjugacy criterion for surface Morse-Smale flows with a finite number of moduli

### Vladislav E. Kruglov, HSE University, Nižnij Novgorod, Russia

8ECM 2021, Portorož

25.06.2021

## The results were obtained in collaboration with Olga V. Pochinka



## Topological conjugacy and equivalence

- Two flows *f<sup>t</sup>*, *f<sup>'t</sup>*: *M* → *M* on a manifold *M* are called *topologically equivalent* if there exists a homeomorphism *h*: *M* → *M* sending trajectories of *f<sup>t</sup>* into trajectories of *f<sup>'t</sup>* preserving orientations of the trajectories.
- Two flows are called *topologically conjugate* if
  *h* ∘ *f<sup>t</sup>* = *f<sup>tt</sup>* ∘ *h*, it means that *h* sends trajectories into
  trajectories preserving not only directions but in addition
  the time of moving.
- To find an invariant showing the class of topological equivalence or topological conjugacy of flows in some class means to get a *topological classification* for the class.

### The Morse-Smale flows

A flow on a surface is called Morse-Smale if its non-wandering set consists of a finite number of hyperbolic fixed points and finite number of hyperbolic limit cycles, besides, there is no trajectories connecting saddle points.



The most important topological invariants for Morse-Smale flows are the *Leontovich-Maier's scheme* [4,5], the *Peixoto's directed graph* [6] and the *Oshemkov-Sharko's molecule* [7].

## The moduli of stability

 A separatrix connecting saddle points gives infinitely many conjugacy classes in one equivalence class, described by a modulus <sup>λ</sup>/<sub>μ</sub> called the *modulus of stability* (Palis, 1978).



- For surface gradient-like flows classes of topological equivalence and topological conjugacy on surfaces coincide (Kruglov, [2]).
- Any limit cycle obviously generates a modulus equal to its period

### The problems solved in the work

- The criterion of the moduli finiteness for the surface Morse-Smale flows;
- Topological classification in sense of conjugacy for surface Morse-Smale flows with a finite number of moduli.

### **Fixed points**

The hyperbolicity of fixed points leads to the following types of fixed points: a sink, a saddle and a source. A flow near a fixed point is topologically conjugate with a linear flow with a sink, saddle or source respectively (Palis, de Melo [9], Robinson [10], Kruglov [2]).



### **Limit cycles**

The hyperbolicity of limit cycles leads to the fact that limit cycles may be only stable or unstable. The neighbourhood of a limit cycle is an annulus or a Möbius band.



### Linearisation near limit cycles

We define a flow  $A^t : \mathbb{R}^2 \to \mathbb{R}^2$  as  $A^t(x, y) = (x, y + t)$ . For  $\mu \in \{-1, 1\}, \lambda \in \{0, 1\}$  and T > 0 let us consider a homeomorphism  $g_{\mu,\lambda,T} : \mathbb{R}^2 \to \mathbb{R}^2$  given by the formula

$$g_{\mu,\lambda,T}(x,y) = (\mu \cdot 2^{(-1)^{\lambda+1}}x, y - T)$$

and the group  $G_{\mu,\lambda,T} = \{g_{\mu,\lambda,T}^n, n \in \mathbb{Z}\}$ . Denote by  $\Pi_{\mu,\lambda,T}$  a space orbit of the action of the group  $G_{\mu,\lambda,T}$  on  $\mathbb{R}^2$  and by  $q_{\mu,\lambda,T} : \mathbb{R}^2 \to \Pi_{\mu,\lambda,T}$  the natural projection. Then  $\Pi_{\mu,\lambda,T}$  is a cylinder for  $\mu = 1$  and a Möbius band for  $\mu = -1$ ; the flow  $A^t$  induces by  $q_{\mu,\lambda,T}$  the flow  $a_{\mu,\lambda,T}^t$  on  $\Pi_{\mu,\lambda,T}$  with unique stable limit cycle  $c_{\mu,\lambda,T} = q_{\mu,\lambda,T}(Oy)$  of the period *T* for  $\lambda = 0$ , and the flow  $a_{\mu,\lambda,T}^t = q_{\mu,\lambda,T}(Oy)$  of the period *T* for  $\lambda = 1$ .

## Linearisation near limit cycles



### Proposition (Irwin [1])

For every hyperbolic limit cycle  $c_i$  of a flow  $\phi^t : S \to S$  there are numbers  $\mu_i \in \{-1, 1\}, \lambda_i \in \{0, 1\}, T_i > 0$  and a neighbourhood  $U_i$  such that  $\phi^t|_{U_i}$  is topologically conjugate to the flow  $a^t_{\mu_i,\lambda_i,T_i}$ .

The limit cycle  $c_i$  is called *a stable, an unstable* for  $\lambda_i = 0, 1$  respectively.

### The unique foliation near limit cycle



Let  $K_i = W_{\Omega_i}^u$  for an unstable cycle  $\Omega_i$  and  $K_i = W_{\Omega_i}^s$  for a stable cycle  $\Omega_i$ , respectively.

### Proposition (Kruglov, Pochinka, Talanova, [3])

There is a unique one-dimensional foliation  $\Xi_i$  in  $K_i$  whose leaves  $\xi_i$  are cross-sections for trajectories of flow  $\phi^t|_{K_i}$  and

 $\phi^{T_i}(z) \in \xi_i, \ \phi^t(z) \notin \xi_i \ for \ 0 < t < T_i, \ if \ z \in \xi_i.$ 

### The moduli finiteness condition

Recall that a modulus of topological conjugacy is an analytical parameter describing infinite many conjugacy classes in the equivalence class.

The first main result of the report is the following.

#### Theorem

A Morse-Smale surface flow has a finite number of moduli iff it has no a trajectory going from one limit cycle to another.

Let *G* be the class of Morse-Smale flow with a finite number of moduli, and let  $\phi^t \in G$ .

# Cutting set and cutting circles. An elementary region

Let  $\mathcal{R} = \bigcup_{\mathfrak{c} \in \Omega^3_{\phi^t}} R_\mathfrak{c}$  be the union of the boundary circles of

cycles'es neighbourhoods. We call  $\mathcal{R}$  a *cutting set* and the connected components of  $\mathcal{R}$  *cutting circles*. Let  $\hat{S} = S \setminus \mathcal{R}$ . We call *an elementary region* a connected component of the set  $\hat{S}$ . The elementary regions, obviously, can be of the following pairwise disjoint types with respect to information about basic sets of  $\phi^t$  in the regions:

1) a region of the type  $\mathcal{L}$  contains exactly one limit cycle;

2) a region of the type  $\mathcal{A}$  contains exactly one source or exactly one sink;

3) a region of the type  $\mathcal{M}$  contains at least one saddle point;

## The directed graph of a flow



### Definition

A directed graph  $\Upsilon_{\phi^t}$  is said to be a *graph of the flow*  $\phi^t \in G$  if (1) the vertices of  $\Upsilon_{\phi^t}$  bijectively correspond to the elementary regions of  $\phi^t$ :

(2) every directed edge of  $\Upsilon_{\phi^t}$ , which joins a vertex *a* with a vertex *b*, corresponds to the cutting circle *R*, which is a common boundary of the regions *A* and *B* corresponding to *a* and *b*, such that any trajectory of  $\phi^t$  passing *R* goes from *A* to *B* by increasing the time.

### Properties of the directed graph

We will call a  $\mathcal{L}$ -,  $\mathcal{A}$ -, or  $\mathcal{M}$ -vertex a vertex of  $\Upsilon_{\phi'}$ , which corresponds to a  $\mathcal{L}$ -,  $\mathcal{A}$ -, or  $\mathcal{M}$ -region accordingly.

**Proposition** 

Let  $\Upsilon_{\phi^t}$  be the directed graph of a flow  $\phi^t \in G$ , then:

1) every  $\mathcal{M}$ -vertex can be connected only with  $\mathcal{L}$ -vertices, furthermore, with every vertex by a single edge;

2) every *A*-vertex can be connected only with a *L*-vertex, furthermore, by a single edge;

3) every  $\mathcal{L}$ -vertex has degree (the number of incident edges) 1 or 2, and if its degree is 2, then both edges either enter the vertex or exit.

## Equipping of the graph $\Upsilon_{\phi'}$

The flows in A-regions can belong to only the two conjugacy classes: a source pool and a sink pool, which we can distinguish by directions of edges incident to A-vertices.

The flows in  $\mathcal{L}$ -regions can belong to only the four equivalence classes:

- an annulus with a stable limit cycle;
- an annulus with an unstable one;
- the Möbius band with a stable one;
- the Möbius band with an unstable one.

But every equivalence class consists of infinitely many conjugacy classes depending on a period of limit cycles. So, let us equip each  $\mathcal{L}$ -vertex with a *cycle modulus*, i.e. the period.

# Equipping of $\mathcal{M}$ -vertex. Constructing a surface M and a gradient-like flow on it

Consider an  $\mathcal{M}$ -region. It can be

- a 2-manifold with a boundary (with "holes");
- a closed surface;

Attach a union *D* of 2-disk to each boundary component of M to get a closed surface *M*.

Let  $f^t: M \to M$  be te flow such that  $f^t|_{\mathcal{M}} = \phi^t|_{\mathcal{M}}$  and that  $\Omega_{f^t}$  has exactly one sink or one source in each connected component of D.



## Equipping of $\mathcal{M}$ -vertex. A cell

Let  $\Omega_{f^t}^0$ ,  $\Omega_{f^t}^1$ ,  $\Omega_{f^t}^2$  be the sets of all sources, saddle points and sinks of  $f^t$  accordingly. By the definition of the region  $\mathcal{M}$  the flow  $f^t$  has at least one saddle point. Let

$$\tilde{M} = M \setminus (\Omega^0_{f^t} \cup W^s_{\Omega^1_{f^t}} \cup W^u_{\Omega^1_{f^t}} \cup \Omega^2_{f^t}).$$

A connected component of  $\tilde{M}$  is called *a cell*.

### **Proposition (Peixoto** [7])

Every cell J of the flow  $f^t$  contains a single sink  $\omega$  and a single source  $\alpha$  in its boundary, and the whole cell is the union of trajectories going from  $\alpha$  to  $\omega$ .

## Equipping of $\mathcal{M}$ -vertex. A triangle region



Let us choose a *t*-curve in each cell *J* which is some usual trajectory in *J*. Let us call an *u*-curve an unstable saddle separatrix with a sink in its closure, an *s*-curve a stable saddle separatrix with a source in its closure. We will call a *triangle region*  $\Delta$  the connecting component of  $\overline{M}$ .

### Proposition (Oshemkov-Sharko [6])

Every triangle region  $\Delta$  is homeomorphic to an open disk and its boundary consists of an unique *t*-curve, an unique *u*-curve and an unique *s*-curve.

## The three-colour graph for a flow

We say that a three-colour graph  $\Gamma_{\mathcal{M}}$  corresponds to  $f^t$  if: 1) the vertices of  $\Gamma_{\mathcal{M}}$  bijectively correspond to the triangle regions of  $\Delta_{f^t}$ ;

2) two vertices of  $\Gamma_{\mathcal{M}}$  are incident to an edge of colour *s*, *t* or *u* if the polygonal regions corresponding to these vertices has a common *s*-, *t*- or *u*-curve; that establishes an one-to-one correspondence between the edges of  $\Gamma_{\mathcal{M}}$  and the colour curves;

### Definition

We say that the graph  $\Gamma_{\mathcal{M}}$  is the three-colour graph of the flow  $f^t$  corresponding to  $\phi^t|_{\mathcal{M}}$ .

## A flow and its three-colour graph



### Equipment of some directed edges

Let us denote by  $\pi_{f^t}$  the correspondence described above between elements of  $f^t$  and  $\Gamma_{\mathcal{M}}$ .

Let *ut*-, *st*- and *su* cycles be the cycles of  $\Gamma_M$  consisting only of the edges of corresponding colours.

### **Proposition**

The projection  $\pi_{f^t}$  gives an one-to-one correspondence between the sets  $\Omega_{f^t}^0$ ,  $\Omega_{f^t}^1$ ,  $\Omega_{f^t}^2$  and the sets of *tu*-cycles, *su*-cycles of the length 4, and *st*-cycles respectively.

By our construction  $M = \mathcal{M} \cup D$  each connected component of D contains one sink  $\omega$  (source  $\alpha$ ) corresponding to  $R_c$  for c of  $\phi^t$ , which corresponds to an  $(\mathcal{M}, \mathcal{L})$ -edge  $((\mathcal{L}, \mathcal{M})$ -edge) of  $\Upsilon_{\phi^t}$ . Thus we induce an orientation from  $R_c$  to the cycle.

## The equipped graph

### Definition

Let  $\Upsilon_{\phi^t}$  be the directed graph of a flow  $\phi^t \in G$ . We will say that  $\Upsilon_{\phi^t}$  is the *equipped graph* of  $\phi^t$  and denote it by  $\Upsilon_{\phi^t}^*$  if:

(1) every  $\mathcal{M}$ -vertex is equipped with a four-colour graph  $\Gamma_{\mathcal{M}}$  corresponding to the flow  $f^t$  constructed before;

(2) every edge  $(\mathcal{M}, \mathcal{L})$   $((\mathcal{L}, \mathcal{M}))$  is equipped with an oriented *tu*-cycle (*st*-cycle)  $\tau_{\mathcal{M}, \mathcal{L}}$  ( $\tau_{\mathcal{L}, \mathcal{M}}$ ) of  $\Gamma_{\mathcal{M}}$  corresponding to the limit cycle  $\mathfrak{c}$  of  $\mathcal{L}$  and oriented consistently with  $R_{\mathfrak{c}}$ .

(3) every  $\mathcal{L}$ -vertex is equipped with the cycle modulus  $T_{c}$ .

## An example of the equipped graph construction



## The classification result

### Definition

Equipped graphs  $\Upsilon_{\phi^{t}}^{*}$  and  $\Upsilon_{\phi^{\prime \prime}}^{*}$  are said to be *isomorphic* if there is an one-to one correspondence  $\xi$  between all edges and vertices of  $\Upsilon_{\phi^{\prime \prime}}^{*}$  and all edges and vertices of  $\Upsilon_{\phi^{\prime \prime}}^{*}$  preserving their equipments in the following way:

(1) the cycle moduli of vertices  $\mathcal{L}$  and  $\xi(\mathcal{L})$  are equal;

(2) for vertices  $\mathcal{M}$  and  $\xi(\mathcal{M})$ , there is an isomorphism  $\psi_{\mathcal{M}}$  of the three-colour graphs  $\Gamma_{\mathcal{M}}$ ,  $\Gamma_{\xi(\mathcal{M})}$  such that  $\psi_{\mathcal{M}}(\tau_{\mathcal{M},\mathcal{L}}) = \tau_{\xi(\mathcal{M}),\xi(\mathcal{L})}$  and the orientations of  $\psi_{\mathcal{M}}(\tau_{\mathcal{M},\mathcal{L}})$  and  $\tau_{\xi(\mathcal{M}),\xi(\mathcal{L})}$  coincide (similarly for  $\tau_{\mathcal{L},\mathcal{M}}$ ).

#### Theorem

Flows  $\phi^t, \phi'^t \in G$  are topologically conjugate if and only if the equipped graphs  $\Upsilon^*_{\phi^t}$  and  $\Upsilon^*_{\phi''}$  are isomorphic.

### **References**

[1] M. C. Irwin. A classification of elementary cycles. Topology, 9:35-47, 1970.

[2] V. E. Kruglov. Topological conjugacy of gradient-like flows on surfaces. Dinamicheskie sistemy, 8(36)(1):15-21, 2018.

[3] V. Kruglov, O. Pochinka, G. Talanova. On functional moduli of surface flows. Proceedings of the International Geometry Center, 13(1): 49-60, 2020.

[4] E. A. Leontovich, A. G. Mayer. On trajectories determining qualitative structure of sphere partition into trajectories. Doklady Akademii nauk SSSR, 14(5):251-257, 1937 (in Russian).

[5] E. A. Leontovich, A. G. Mayer. On a scheme determining the topological structure of the separation of trajectories. Dokl. Akad. Nauk SSSR (N.S.), 103:557-560, 1955 (in Russian).

### References

[6] M. M. Peixoto. On the classification of flows on 2-manifolds. In Dynamical systems (Proc. Sympos., Univ. Bahia, Salvador, 1971), pages 389-419, 1973.

[7] A. A. Oshemkov, V. V. Sharko. On the classification of Morse-Smale flows on two-dimensional manifolds. Mat. Sb., 189(8):93-140, 1998.

[8] J. Palis. A differentiable invariant of topological conjugacies and moduli of stability. Asterisque, 51:335-346, 1978.

[9] J. Palis J., W. de Melo. (1982). Geometric theory of dynamical systems. New York, Heidelberg, Berlin, Springer-Verlag.

[10] C. Robinson (1995). Dynamical systems: stability, symbolic dynamics, and chaos. CRC Press, Boca Raton, Ann Arbor, London, Tokyo.

## THANKS FOR YOUR ATTENTION