Approximate Calculation of Triple Integrals of Rapidly Oscillating Functions using Different Types of Information about Functions

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- The integrals of highly oscillating functions of many variables are one of the central concepts of digital signal and image processing.
- Nowadays, methods for digital signal and image processing are widely used in scientific and technical areas.
- **Current stage** of research in
 - astronomy, radiology, computed tomography, holography and radar
 - is characterized by broad use of digital technologies, algorithms and methods.
- Correspondingly, an issue of development new or improvement of known mathematical models arose, especially for new types of input information.

- There are the cases when input information about function is given: on the set of traces of the function on planes; set of traces of the function on lines; and set of values of the function in the points.
- The report is dedicated to the improvement of mathematical models of digital signal processing and imaging by the example of constructing formulas of approximate calculation of integrals of highly oscillating functions of two and three variables.

- Oscillatory integrals are present in various applications, but it is difficult to compute them by standard methods.
- There is a great number of articles where problems of highly-oscillating functions in regular case are discussed.
- The oldest paper has been published by L.N.G.Filon (1928); also it is necessary to mention Y.L.Luke (1954);

I.Zamfirescu (1963);

N. Bakhvalov & L. Vasileva (1968)

D.Levin (1982), etc.

The full analysis of these methods is presented by A. Iserles in

Iserles, A. On the numerical quadrature of highly–oscillating integrals I: Fourier transforms. IMA J. Numer. Anal. 24, 365–391 (2004)

J. Gao and A. Iserles, Error analysis of the extended Filon-type method for highly oscillatory integrals. Tech. Re-ports Numerical Analysis (NA2016/03) DAMPT: University of Cambridge, 2016.

• by V. Milovanovic in

Milovanovic G. V., Stanic M.P., Numerical Integration of Highly Oscillating Functions. Analytic Number Theory, Approximation Theory, and Special Functions, 2014, pp. 613-649.

Two and three dimensional methods for computation of integrals of highly oscillating functions in regular case are **also discussed** in various papers. One dimensional methods are extended to the multidimensional integration.

The full analysis of these methods is presented by A. Iserles in

Iserles, A., S. P. Norsett, From high oscillation to rapid approximation III: Multivariate expansions // Tech. Reports Numerical Analysis (NA2007/01)/ DAMPT – University of Cambridge. – 37 p.

• by V.K. Zadiraka in

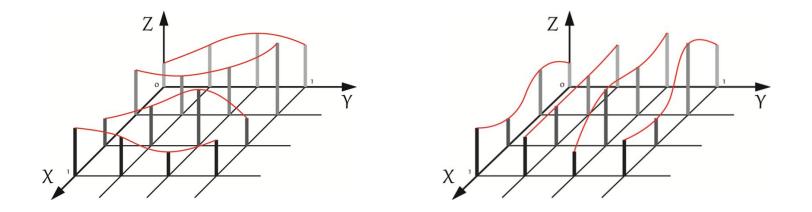
I. V. Sergienko, V.K. Zadiraka, O. M. Lytvyn, S.S. Melnikova, O.P. Nechuyviter, Optimal Algorithms of Calculation of Highly Oscillatory Integrals and their Applications. Monography, Tom 1. Algorithms, Kiev, 2011, p. 447.

In this work the **problem of computing rapidly oscillating integrals** of differentiable functions **using various information operators** is considered.

- At the beginning in this report we present formulas of the evaluating of two dimensions of Fourier coefficients with using piece-wise splines.
- These formulas are constructing in two cases: input information about function is a set of traces of function on lines and a set of values of the function in the points.
- The main advantages of methods are high exactness of approximation and less amount of information about function.

Definition 1. Under the traces of function f(x, y) on the lines $x_k = k\Delta - \Delta/2$, $y_j = j\Delta - \Delta/2$, $k, j = \overline{1, \ell}$, $\Delta = 1/\ell$ we understand a function of

one variable $f(x_k, y)$, $0 \le y \le 1$ or $f(x, y_j)$, $0 \le x \le 1$.



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Let

$$Jf(x,y) = \sum_{k=1}^{\ell} f(x_{k},y) h_{0k}(x) + \sum_{j=1}^{\ell} f(x,y_{j}) H_{0j}(y) - \sum_{k=1}^{\ell} \sum_{j=1}^{\ell} f(x_{k},y_{j}) h_{0k}(x) H_{0j}(y), \quad (1)$$

$$h_{0k}(x) = \begin{cases} 1, x \in X_{k}, \\ 0, x \notin X_{k}, \end{cases} k = \overline{1,\ell}, \quad H_{0j}(y) = \begin{cases} 1, y \in Y_{j}, \\ 0, y \notin Y_{j}, \end{cases} j = \overline{1,\ell}, \\ X_{k} = [x_{k-1/2}, x_{k+1/2}], \quad Y_{j} = [y_{j-1/2}, y_{j+1/2}], \\ x_{k} = k\Delta - \Delta/2, \quad y_{j} = j\Delta - \Delta/2, \quad k, j = \overline{1,\ell}, \quad \Delta = 1/\ell. \end{cases}$$

We consider $H^{2,r}(M,\widetilde{M}), r \ge 0$ – the class of functions, which are defined on the domain $G = [0,1]^2$ and

$$\left|f^{\left(r,0\right)}(x,y)\right| \leq M, \quad \left|f^{\left(0,r\right)}(x,y)\right| \leq M, \ r \neq 0, \ \left|f^{\left(r,r\right)}(x,y)\right| \leq \widetilde{M}, \quad r \geq 0.$$

For numerical calculating of two-dimensional Fourier coefficients

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Theorem 1. Suppose that $f(x,y) \in H^{2,1}(M,\widetilde{M})$. Let functions f(x,y) be

defined by $N = 2\ell$ traces $f(x_k, y)$, $k = \overline{1, \ell}$, $f(x, y_j)$, $j = \overline{1, \ell}$ on the system of

perpendicular lines in domain $G = [0,1]^2$. It is true that

$$\rho\left(I_1^2(m,n),\Phi_1^2(m,n)\right) = \left|I_1^2(m,n) - \Phi_1^2(m,n)\right| \le \frac{\widetilde{M}}{16\ell^2} = \frac{\widetilde{M}}{4N^2}.$$

- We also can built cubature formula for calculating of two-dimensional Fourier coefficients in case when information about f(x,y) is a set of values of the function in the points.
- The main advantages of this formula are high exactness of approximation, the opportunity to decrease the amount of information about function during the calculation.

Let
$$\begin{split} \tilde{J}f\left(x,y\right) &= \sum_{k=1}^{\ell} \sum_{\tilde{j}=1}^{\ell^{2}} f\left(x_{k}, \tilde{y}_{\tilde{j}}\right) h_{0k}\left(x\right) \tilde{H}_{0\tilde{j}}\left(y\right) + \sum_{j=1}^{\ell} \sum_{\tilde{k}=1}^{\ell^{2}} f\left(\tilde{x}_{\tilde{k}}, y_{j}\right) \tilde{h}_{0\tilde{k}}\left(x\right) H_{0j}\left(y\right) - \\ &- \sum_{k=1}^{\ell} \sum_{j=1}^{\ell} f\left(x_{k}, y_{j}\right) h_{0k}\left(x\right) H_{0j}\left(y\right), \\ X_{k} &= \left[x_{k-1/2}, x_{k+12}\right], \ Y_{j} &= \left[y_{j-1/2}, y_{j+1/2}\right], \quad \tilde{X}_{\tilde{k}} &= \left[\tilde{x}_{\tilde{k}-1/2}, \tilde{x}_{\tilde{k}+1/2}\right], \ \tilde{Y}_{\tilde{j}} &= \left[\tilde{y}_{\tilde{j}-1/2}, \tilde{y}_{\tilde{j}+1/2}\right], \\ h_{0k}\left(x\right) &= \begin{cases} 1, x \in X_{k}, \\ 0, x \notin X_{k}, \end{cases} \quad k = \overline{1, \ell}, \qquad H_{0j}\left(y\right) = \begin{cases} 1, y \in Y_{j}, \\ 0, y \notin Y_{j}, \end{cases} \quad j = \overline{1, \ell}, \\ \tilde{h}_{0\tilde{k}}\left(x\right) &= \begin{cases} 1, x \in \tilde{X}_{\tilde{k}}, \\ 0, x \notin \tilde{X}_{\tilde{k}}, \end{cases} \quad \tilde{k} = \overline{1, \ell^{2}}, \qquad \tilde{H}_{0\tilde{j}}\left(y\right) = \begin{cases} 1, y \in \tilde{Y}_{\tilde{j}}, \\ 0, y \notin \tilde{Y}_{\tilde{j}}, \end{cases} \quad j = \overline{1, \ell^{2}}, \\ x_{k} &= k\Delta - \frac{\Delta}{2}, \ y_{j} &= j\Delta - \frac{\Delta}{2}, \ k, j = \overline{1, \ell}, \end{cases} \quad \Delta = \frac{1}{\ell}, \ \tilde{x}_{\tilde{k}} &= \tilde{k}\Delta_{1} - \frac{\Delta_{1}}{2}, \ \tilde{y}_{\tilde{j}} &= \tilde{j}\Delta_{1} - \frac{\Delta_{1}}{2}, \ \tilde{k}, \tilde{j} &= \overline{1, \ell^{2}}, \end{cases}$$

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(5)

For numerical calculating of two-dimensional Fourier coefficients

$$I_{1}^{2}(m,n) = \int_{0}^{1} \int_{0}^{1} f(x,y) \sin 2\pi mx \sin 2\pi ny dx dy$$

we suggest formula
$$\widetilde{\Phi}_{1}^{2}(m,n) = \int_{0}^{1} \int_{0}^{1} \tilde{J}f(x,y) \sin 2\pi mx \sin 2\pi ny dx dy,$$
(6)
$$\widetilde{\Phi}_{1}^{2}(m,n) = \sum_{k=1}^{\ell} \sum_{j=1}^{\ell^{2}} f(x_{k},\tilde{y}_{j}) \int_{x_{k-\frac{1}{2}}}^{x_{k+\frac{1}{2}}} \sin 2\pi mx dx \int_{y_{j-\frac{1}{2}}}^{y_{j+\frac{1}{2}}} \sin 2\pi ny dy +$$
$$+ \sum_{j=1}^{\ell} \sum_{k=1}^{\ell^{2}} f(\tilde{x}_{k},y_{j}) \int_{x_{k-\frac{1}{2}}}^{\tilde{x}_{k+\frac{1}{2}}} \sin 2\pi mx dx \int_{y_{j-\frac{1}{2}}}^{y_{j+\frac{1}{2}}} \sin 2\pi mx dx \int_{$$

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Theorem 2. Suppose that $f(x, y) \in H^{2,1}(M, \widetilde{M})$. Let functions f(x, y) be defined by $f(x_k, \tilde{y}_{\tilde{j}}), f(\tilde{x}_{\tilde{k}}, y_j), k, j = \overline{1, \ell}, \tilde{k}, \tilde{j} = \overline{1, \ell^2}$ knots on domain $G = [0, 1]^2$. It is true that $\rho\left(I_1^2(m,n), \widetilde{\Phi}_1^2(m,n)\right) \le \frac{M}{2\ell^2} + \frac{M}{16\ell^2} = O\left(\frac{1}{\sqrt{N}}\right), \quad N = \ell^4.$ X

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We compare cubature formula with formula

$$\widehat{\Phi}_{1}^{2}(m,n) = \sum_{k=1}^{\ell^{2}} \sum_{j=1}^{\ell^{2}} f(x_{k}, y_{j}) \int_{x_{k-\frac{1}{2}}}^{x_{k+\frac{1}{2}}} \sin 2\pi m x dx \int_{y_{j-\frac{1}{2}}}^{y_{j+\frac{1}{2}}} \sin 2\pi n y dy.$$
(8)
It is necessary to note that $\rho\left(I_{1}^{2}(m,n), \widehat{\Phi}_{1}^{2}(m,n)\right) \leq O\left(\frac{1}{\sqrt{N}}\right), \quad N = \ell^{4}.$

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We look for the difference between such characteristics:

- the amount of values of the function in the points Q for $\tilde{\Phi}_1^2(m,n)$ and \hat{Q} for $\hat{\Phi}_1^2(m,n)$;
- time spent T for $\widetilde{\Phi}_1^2(m,n)$ and \widehat{T} for $\widehat{\Phi}_1^2(m,n)$;

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- the amount of memory *P* for $\tilde{\Phi}_1^2(m,n)$ and \hat{P} for $\hat{\Phi}_1^2(m,n)$ in computing.

Example

Calculations were done for function $f(x, y) = \sin(x+y)$ in Wolfram Mathematica 8.

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Table 1.

m	n	l	ε_1	$Q = 2\ell^3 - \ell^2$	ε ₂	$\widehat{Q} = \ell^4$
4	4	10	1.01-10 ⁻⁸	1900	1.01-10 ⁻⁸	10000
		25	2.66.10 ⁻¹⁰	30625	2.62.10 ⁻¹⁰	390625
5	5	25	1.69.10 ⁻¹⁰	30625	1.67.10 ⁻¹⁰	390625
		35	4.43.10 ⁻¹¹	84525	4.36-10 ⁻¹¹	1500625
5	6	20	3.43.10 ⁻¹⁰	15600	3.40.10 ⁻¹⁰	160000
		30	6.83-10 ⁻¹¹	53100	6.73 - 10 ⁻¹¹	810000
		40	2.16.10 ⁻¹¹	126400	2.12.10 ⁻¹¹	2560000

Table 2.

m	п	Ł	Т,с	\widehat{T} , c	Р,б	<i>P</i> ,6
4	4	10	0.4	2.0	4010868	40311244
		25	8.4	91.1	39979828	48502900
5	5	25	7.1	84.7	42660708	42863484
		35	21.6	337.9	43036868	43188236
5	6	20	3.3	24.2	44500004	44659660
		30	8.4	165.0	44843860	44991564
		40	13.4	465.5	45150228	45416260

The research is dedicated to the improvement of mathematical models of digital signal processing and imaging by the example of **constructing cubature formulas** of approximate calculation **of integrals**

$$I_1^3(m,n,p) = \int_0^1 \int_0^1 \int_0^1 f(x,y,z) \sin 2\pi mx \sin 2\pi ny \sin 2\pi pz dx dy dz$$

of highly oscillatory functions of three variables.

The feature of the proposed cubature formulas is using the input information about function as

- a set of traces of function on planes;
- a set of traces of function on lines;
- a set of values of the function in the points.

Definition 2. The traces of function of three variables on the planes $x_k = k\Delta - \Delta/2$, $y_j = j\Delta - \Delta/2$, $z_s = s\Delta - \Delta/2$, $k, j, s = \overline{1,\ell}$, $\Delta = 1/\ell$

are understood as function of two variables

 $f(x_k, y, z), \ 0 \le y \le 1, \ 0 \le z \le 1, \ f(x, y_j, z), \ 0 \le x \le 1, \ 0 \le z \le 1, \ f(x, y, z_s), \ 0 \le x \le 1, \ 0 \le y \le 1.$

Definition 3. The traces of function of three variables on the lines

$$\left\{ \left(x, y, z\right): x = x_k, y = y_j, \quad x_k = k\Delta - \frac{\Delta}{2}, y_j = j\Delta - \frac{\Delta}{2}, \Delta = \frac{1}{\ell}, k, j = \overline{1, \ell}, \qquad 0 \le z \le 1 \right\}$$

are understood as function of one variables

 $f(x_k, y_j, z), \quad 0 \le z \le 1.$

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1 case: the input information about function is a set of traces of function on planes

Let

$$J_{1}f(x, y, z) = \sum_{k=1}^{\ell} f(x_{k}, y, z)h_{1k}^{0}(x), \quad J_{2}f(x, y, z) = \sum_{j=1}^{\ell} f(x, y_{j}, z)h_{2j}^{0}(y), \quad (9)$$

$$J_{3}f(x, y, z) = \sum_{s=1}^{\ell} f(x, y, z_{s})h_{3s}^{0}(z), \quad X_{k} = [x_{k-1/2}, x_{k+1/2}], \quad Y_{j} = [y_{j-1/2}, y_{j+1/2}], \quad Z_{s} = [z_{s-1/2}, z_{s+1/2}], \quad h_{1k}^{0}(x) = \begin{cases} 1, x \in X_{k}, \\ 0, x \notin X_{k}, \end{cases} \quad h_{2j}^{0}(y) = \begin{cases} 1, y \in Y_{j}, \\ 0, y \notin Y_{j}, \end{cases} \quad h_{3s}^{0}(z) = \begin{cases} 1, z \in Z_{s}, \\ 0, z \notin Z_{s}, \end{cases} \quad x_{k} = k\Delta - \frac{\Delta}{2}, \quad y_{j} = j\Delta - \frac{\Delta}{2}, \quad z_{s} = s\Delta - \frac{\Delta}{2}, \quad \Delta = \frac{1}{\ell}, \ k, j, s = \overline{1, \ell}. \end{cases}$$

1 case: the input information about function is a set of traces of function on planes

Operator

$$Jf(x, y, z) = J_1 f(x, y, z) + J_2 f(x, y, z) + J_3 f(x, y, z) - J_1 J_2 f(x, y, z) - J_2 J_3 f(x, y, z) - J_1 J_3 f(x, y, z) + J_1 J_2 J_3 f(x, y, z)$$
(10)

has properties:

$$Jf(x_k, y, z) = f(x_k, y, z), \quad k = \overline{1, \ell}, \quad Jf(x, y_j, z) = f(x, y_j, z), \quad j = \overline{1, \ell},$$

$$Jf(x, y, z_s) = f(x, y, z_s), \quad s = \overline{1, \ell}.$$
(11)

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1 case: the input information about function is a set of traces of function on planes

Let

$$H_1^{3,1}\left(M,\widetilde{M}\right) = \left\{ f(x,y,z) : \left| f^{(1,0,0)}(x,y,z) \right| \le M, \quad \left| f^{(0,1,0)}(x,y,z) \right| \le M, \quad \left| f^{(0,0,1)}(x,y,z) \right| \le M, \quad \left| f^{(1,1,1)}(x,y,z) \right| \le \widetilde{M} \right\}.$$

Theorem 3. Cubature formula

$$\Phi_1^3(m,n,p) = \int_0^1 \int_0^1 \int_0^1 Jf(x,y,z) \sin 2\pi mx \sin 2\pi ny \sin 2\pi pz dx dy dz$$
(12)

has the following error of approach $\left|I_{1}^{3}(m,n,p)-\Phi_{1}^{3}(m,n,p)\right| \leq \frac{\widetilde{M}}{64\ell^{3}}.$

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<u>2 case: the input information about function is a set of traces of function on lines</u></u>

Let

$$\widetilde{J}_{1}f(x, y, z) = \sum_{k=1}^{\ell^{3/2}} f(\widetilde{x}_{\tilde{k}}, y, z)\widetilde{h}_{1\tilde{k}}^{0}(x) , \quad \widetilde{J}_{2}f(x, y, z) = \sum_{\tilde{j}=1}^{\ell^{3/2}} f(x, \widetilde{y}_{\tilde{j}}, z)\widetilde{h}_{2\tilde{j}}^{0}(y) , \\
\widetilde{J}_{3}f(x, y, z) = \sum_{\tilde{s}=1}^{\ell^{3/2}} f(x, y, \widetilde{z}_{\tilde{s}})\widetilde{h}_{3\tilde{s}}^{0}(z) , \\
\widetilde{h}_{1\tilde{k}}^{0}(x) = \begin{cases} 1, x \in \widetilde{X}_{\tilde{k}}, & \tilde{h}_{2\tilde{j}}^{0}(y) = \begin{cases} 1, y \in \widetilde{Y}_{\tilde{j}}, & \tilde{h}_{3\tilde{s}}^{0}(z) = \begin{cases} 1, z \in \widetilde{Z}_{\tilde{s}}, \\ 0, y \notin \widetilde{Y}_{\tilde{j}}, & \tilde{h}_{3\tilde{s}}(z) = \begin{cases} 1, z \in \widetilde{Z}_{\tilde{s}}, \\ 0, z \notin \widetilde{Z}_{\tilde{s}}, \end{cases}, \\
\widetilde{x}_{\tilde{k}} = \tilde{k} \Delta_{1} - \frac{\Delta_{1}}{2}, & \widetilde{y}_{\tilde{j}} = \tilde{j} \Delta_{1} - \frac{\Delta_{1}}{2}, & \widetilde{z}_{\tilde{s}} = \tilde{s} \Delta_{1} - \frac{\Delta_{1}}{2}, & \Delta_{1} = \frac{1}{\ell^{3/2}}, & \tilde{k}, \tilde{j}, \tilde{s} = \overline{1, \ell^{3/2}}. \end{cases}$$
(13)

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2 case: the input information about function is a set of traces of function on lines We define operator

$$\widetilde{J}f(x,y,z) = J_{1}\widetilde{J}_{2}f(x,y,z) + J_{1}\widetilde{J}_{3}f(x,y,z) - J_{1}\widetilde{J}_{2}\widetilde{J}_{3}f(x,y,z) + J_{2}\widetilde{J}_{1}f(x,y,z) + + J_{2}\widetilde{J}_{3}f(x,y,z) - J_{2}\widetilde{J}_{1}\widetilde{J}_{3}f(x,y,z) + J_{3}\widetilde{J}_{1}f(x,y,z) + J_{3}\widetilde{J}_{2}f(x,y,z) - J_{3}\widetilde{J}_{1}\widetilde{J}_{2}f(x,y,z) - - J_{1}J_{2}f(x,y,z) - J_{1}J_{3}f(x,y,z) - J_{2}J_{3}f(x,y,z) + J_{1}J_{2}J_{3}f(x,y,z) .$$

$$(14)$$

on the following class of function

$$H_1^{3,1}(M,\overline{M},\widetilde{M}) : |f^{(1,0,0)}(x,y,z)| \le M, |f^{(0,1,0)}(x,y,z)| \le M, |f^{(0,0,1)}(x,y,z)| \le M, |f^{(1,0,1)}(x,y,z)| \le M, |f^{(1,1,0)}(x,y,z)| \le \overline{M}, |f^{(1,1,0)}(x,y,z)| \le \overline{M}.$$

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2 case: the input information about function is a set of traces of function on lines

Theorem 4. Cubature formula

$$\widetilde{\Phi}_{1}^{3}(m,n,p) = \int_{0}^{1} \int_{0}^{1} \int_{0}^{1} \int_{0}^{1} \widetilde{J}f(x,y,z)\sin 2\pi mx \sin 2\pi ny \sin 2\pi pz dx dy dz$$

(15)

has the following error of approach
$$\left|I_1^3(m,n,p)-\widetilde{\Phi}_1^3(m,n,p)\right| \le \left(\frac{\widetilde{M}}{64}+\frac{3\overline{M}}{16}\right)\frac{1}{\ell^3}.$$

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3 case: the input information about function is a set of values of the function in the points

Let $\overline{J}_{1}f(x, y, z) = \sum_{\overline{k}=1}^{\ell^{3}} f(\overline{x}_{\overline{k}}, y, z)\overline{h}_{1\overline{k}}^{0}(x), \ \overline{J}_{2}f(x, y, z) = \sum_{\overline{j}=1}^{\ell^{3}} f(x, \overline{y}_{\overline{j}}, z)\overline{h}_{2\overline{j}}^{0}(y),$ $\overline{J}_{3}f(x, y, z) = \sum_{\overline{s}=1}^{\ell^{3}} f(x, y, \overline{z}_{\overline{s}})\overline{h}_{3\overline{s}}^{0}(z),$ (16)

$$\overline{h}_{1\overline{k}}^{0}(x) = \begin{cases} 1, x \in \overline{X}_{\overline{k}}, \\ 0, x \notin \overline{X}_{\overline{k}}, \end{cases}, \quad \overline{h}_{2\overline{j}}^{0}(y) = \begin{cases} 1, y \in \overline{Y}_{\overline{j}}, \\ 0, y \notin \overline{Y}_{\overline{j}}, \end{cases}, \quad \overline{h}_{3\overline{s}}^{0}(z) = \begin{cases} 1, z \in \overline{Z}_{\overline{s}}, \\ 0, z \notin \overline{Z}_{\overline{s}}, \end{cases},$$
$$\overline{x}_{\overline{k}} = \overline{k}\Delta_{2} - \frac{\Delta_{2}}{2}, \quad \overline{y}_{\overline{j}} = \overline{j}\Delta_{2} - \frac{\Delta_{2}}{2}, \quad \overline{z}_{\overline{s}} = \overline{s}\Delta_{2} - \frac{\Delta_{2}}{2}, \quad \Delta_{2} = \frac{1}{\ell^{3}}, \quad \overline{k}, \overline{j}, \overline{s} = \overline{1, \ell^{3}}.$$

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3 case: the input information about function is a set of of values of the function in the points We define operator

$$\overline{J}f(x,y,z) = J_1 \widetilde{J}_2 \overline{J}_3 f(x,y,z) + J_1 \widetilde{J}_3 \overline{J}_2 f(x,y,z) - J_1 \widetilde{J}_2 \widetilde{J}_3 f(x,y,z) + J_2 \widetilde{J}_1 \overline{J}_3 f(x,y,z) + J_2 \widetilde{J}_3 \overline{J}_1 f(x,y,z) - J_2 \widetilde{J}_1 \widetilde{J}_3 f(x,y,z) +$$
(17)

$$+J_3\widetilde{J}_1\overline{J}_2f(x,y,z)+J_3\widetilde{J}_2\overline{J}_1f(x,y,z)-J_3\widetilde{J}_1\widetilde{J}_2f(x,y,z)-$$

$$-J_1J_2\overline{J}_3f(x,y,z)-J_1J_3\overline{J}_2f(x,y,z)-J_2J_3\overline{J}_1f(x,y,z)+J_1J_2J_3f(x,y,z).$$

Theorem 5. Cubature formula

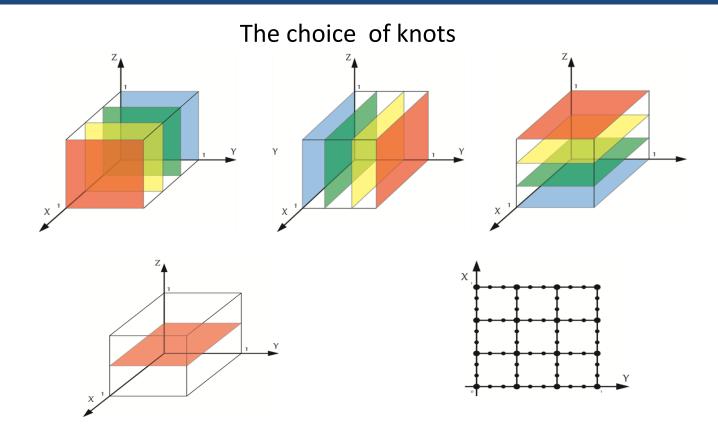
$$\overline{\Phi}_{1}^{3}(m,n,p) = \int_{0}^{1} \int_{0}^{1} \int_{0}^{1} \overline{J}f(x,y,z)\sin 2\pi mx \sin 2\pi ny \sin 2\pi pz dx dy dz$$

has the following error of approach $\left|I_1^3(m,n,p)-\overline{\Phi}_1^3(m,n,p)\right| \le \left(\frac{\overline{M}}{64}+\frac{3\overline{M}}{16}+\frac{9}{4}M\right)\frac{1}{\ell^3}$.

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THREE DIMENSIONAL CLASSICAL CASE

Theorem 6. Let

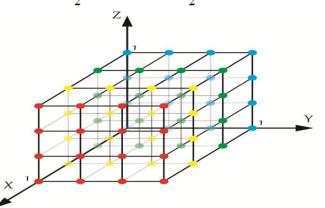
$$H_1^{3,1}(M) = \{ f(x, y, z) : \left| f^{(1,0,0)}(x, y, z) \right| \le M, \left| f^{(0,1,0)}(x, y, z) \right| \le M, \left| f^{(0,0,1)}(x, y, z) \right| \le M \},$$

then cubature formula

$$\widehat{\Phi}_{1}^{3}(m,n,p) = \sum_{\overline{k}=1}^{\ell^{3}} \sum_{\overline{j}=1}^{\ell^{3}} \sum_{\overline{s}=1}^{\ell^{3}} f\left(\overline{x}_{\overline{k}}, \overline{y}_{\overline{j}}, \overline{z}_{\overline{s}}\right) \int_{\overline{x}_{\overline{k}-\frac{1}{2}}}^{\overline{x}_{\overline{k}+\frac{1}{2}}} \sin 2\pi m x dx \int_{\overline{y}_{\overline{j}-\frac{1}{2}}}^{\overline{y}_{\overline{j}+\frac{1}{2}}} \sin 2\pi n y dy \int_{\overline{z}_{\overline{s}-\frac{1}{2}}}^{\overline{z}_{\overline{s}+\frac{1}{2}}} \sin 2\pi p z dz$$

has the following error of approach:

$$\left|I_1^3(m,n,p) - \widehat{\Phi}_1^3(m,n,p)\right| \le \frac{3}{4}M\frac{1}{\ell^3}.$$



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Computer experiment

Calculation of $I_1^3(25,25,25)$ for $f(x,y,z) = \sin(x+y+z)$, $\ell = 4$ by proposed and classic formulas:					
		$\bar{\Phi}_1^3(m,n,p)$	$\widehat{\Phi}_1^3(m,n,p)$		
	E	$3,1 \cdot 10^{-11}$	$1,0.10^{-13}$		
	Q	2048	262144		
	Μ	78209932	78594620		

E – calculation accuracy, Q – amount of knots, M – storage capacity, T – time of calculation.

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TWO AND THREE DIMENSIONAL IRREGULAR CASE

- Iserles A., On the numerical quadrature of highly oscillating integrals II: Irregular oscillators / A. Iserles // IMA J. Numer. Anal. 2005. № 25. Р. 25–44.
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A two-dimensional integral from highly oscillating functions of general view is defined as

$$I^{2}(\omega) = \int_{0}^{1} \int_{0}^{1} f(x, y) e^{i\omega g(x, y)} dxdy$$

for f(x, y), $g(x, y) \in H^{2,1}(M, \overline{M})$.

We are looking for two operators: the first

$$Jf(x,y) = \sum_{k=1}^{\ell_1} f(x_k,y) h \mathbb{1}_{0k}(x) + \sum_{j=1}^{\ell_1} f(x,y_j) H \mathbb{1}_{0j}(y) - \sum_{k=1}^{\ell_1} \sum_{j=1}^{\ell_1} f(x_k,y_j) h \mathbb{1}_{0k}(x) H \mathbb{1}_{0j}(y)$$

and the second one

$$Og(x,y) = \sum_{p=1}^{\ell_2} f(x_p,y) h 2_{0p}(x) + \sum_{s=1}^{\ell_2} f(x,y_s) H 2_{0s}(y) - \sum_{p=1}^{\ell_2} \sum_{s=1}^{\ell_2} f(x_p,y_s) h 2_{0p}(x) H 2_{0s}(y).$$

$$\begin{split} h1_{0k}(x) &= \begin{cases} 1, x \in X1_k, \\ 0, x \notin X1_k, \end{cases} k = \overline{1, \ell_1}, \quad H1_{0j}(y) = \begin{cases} 1, y \in Y1_j, \\ 0, y \notin Y1_j, \end{cases} j = \overline{1, \ell_1}, \\ X1_k &= \begin{bmatrix} x_{k-1/2}, x_{k+1/2} \end{bmatrix}, Y1_j = \begin{bmatrix} y_{j-1/2}, y_{j+1/2} \end{bmatrix}, \\ x_k &= k\Delta_1 - \Delta_1 / 2, \quad y_j = j\Delta_1 - \Delta_1 / 2, \quad k, j = \overline{1, \ell_1}, \quad \Delta_1 = 1 / \ell_1, \\ h2_{0p}(x) &= \begin{cases} 1, x \in X2_p, \\ 0, x \notin X2_p, \end{cases} p = \overline{1, \ell_1}, \quad H2_{0j}(y) = \begin{cases} 1, y \in Y2_s, \\ 0, y \notin Y2_s, \end{cases} s = \overline{1, \ell_1}, \\ X1_p &= \begin{bmatrix} x_{p-1/2}, x_{p+1/2} \end{bmatrix}, Y1_s = \begin{bmatrix} y_{s-1/2}, y_{s+1/2} \end{bmatrix}, \\ x_p &= p\Delta_2 - \Delta_2 / 2, \quad y_s = s\Delta_2 - \Delta_2 / 2, \text{ p, s} = \overline{1, \ell_2}, \quad \Delta_2 = 1 / \ell_2. \end{split}$$

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The following cubature formula $\Phi^2(\omega) = \int_0^1 \int_0^1 Jf(x, y) e^{i\omega Og(x, y)} dxdy$

is suggesting for numerical calculation of $I^2(\omega) = \int_0^1 \int_0^1 f(x, y) e^{i\omega g(x, y)} dxdy$.

Theorem 6. Suppose that $f(x, y), g(x, y) \in H^{2,1}(M, \overline{M})$. Let functions f(x, y), g(x, y) be defined by $N = 2\ell_1 + 2\ell_2$ traces $f(x_k, y), k = \overline{1, \ell_1}, f(x, y_j), j = \overline{1, \ell_1}$ and $g(x_p, y), p = \overline{1, \ell_2}, g(x, y_s), s = \overline{1, \ell_2}$ on the systems of perpendicular lines in domain $G = [0,1]^2$. It is true that

 $\rho(I^2(\omega), \Phi^2(\omega)) =$

$$= \left| \int_{0}^{1} \int_{0}^{1} f(x, y) e^{i\omega g(x, y)} dx dy - \int_{0}^{1} \int_{0}^{1} Jf(x, y) e^{i\omega Og(x, y)} dx dy \right| \leq \frac{\widetilde{M}}{16} \frac{1}{\ell_1^2} + \widetilde{M} \min\left(2; \frac{\widetilde{M}\omega}{16} \frac{1}{\ell_2^2}\right).$$

It is necessary to construct and investigate the cubature formula of the approximate calculation of the integral of highly oscillating function in a general case

$$I^{3}(\omega) = \int_{0}^{1} \int_{0}^{1} \int_{0}^{1} f(x, y, z) e^{i\omega g(x, y, z)} dx dy dz,$$

when the following information is given by traces on the planes.

The following cubature formula

$$\Phi^{3}(\omega) = \int_{0}^{1} \int_{0}^{1} \int_{0}^{1} Jf(x, y, z) e^{i\omega Og(x, y, z)} dx dy dz$$

is proposed for numerical calculation of integral $I^{3}(\omega)$.

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Theorem 7. Suppose that $f(\mathbf{x},\mathbf{y},\mathbf{z}) \in H^{3,1}(M,\widetilde{M})$, $g(x, y, z) \in H^{3,1}(M, \widetilde{M})$. Let functions f(x, y, z), g(x, y, z) be defined by $N = 3\ell_1 + 3\ell_2$ traces $f(x_k, y, z), f(x, y_j, z), f(x, y, z_s), k, j, s = \overline{1, \ell_1}$ and $g(\tilde{x}_p, y, z), g(x, \tilde{y}_q, z), g(x, y, \tilde{z}_r), p, q, r = \overline{1, \ell_2}$ on the systems of perpendicular planes in domain $G = [0,1]^3$. It is true that

$$\rho\left(I^{3}(\omega), \Phi^{3}(\omega)\right) \leq \frac{\widetilde{M}}{64} \frac{1}{\ell_{1}^{3}} + \widetilde{M}\min\left(2; \frac{\widetilde{M}\omega}{64} \frac{1}{\ell_{2}^{3}}\right).$$

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Information about functions f(x, y, z) and g(x, y, z)is given by the corresponding traces of functions on mutually perpendicular planes. The Table 3 shows the results of calculations $I^3(\omega)$ for $f(x, y, z) = \sin(x + y + z)$ and $g(x, y, z) = \cos(x + y + z)$ for different ℓ_1 , ℓ_2 and for $\omega = 2\pi$, $\omega = 5\pi$, $\omega = 10\pi$. For each case, table 3 shows the value of the obtained approximation error

$$\varepsilon = \left| I^{3}(\omega) - \Phi^{3}(\omega) \right|,$$
$$E = \frac{\widetilde{M}}{64} \frac{1}{\ell_{1}^{3}} + \widetilde{M} \min\left(2; \frac{\widetilde{M}\omega}{64} \frac{1}{\ell_{2}^{3}}\right).$$

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Table 3 – Calculation $I^3(\omega)$ by cubature formula $\Phi^3(\omega)$

l	ω	$\operatorname{Re}\left(\Phi^{3}\left(\omega\right)\right)$	$\operatorname{Im}\left(\Phi^{3}\left(\omega ight) ight)$	ε	Ε
5	10π	-0,00180433697415137	0,000356265110351913	7,39.10 ⁻⁴	4,05·10 ⁻³
10	10π	-0,00140102828305083	-0,000261065518418426	3,62.10 ⁻⁶	5,06 · 10 ⁻⁴
15	10 π	-0,00139749596727245	-0,000261837407624295	2,41.10 ⁻⁷	1,05.10 ⁻⁴
20	10π	-0,00035388799218903	-0,000260805717278864	1,39.10 ⁻⁶	6,33·10 ⁻⁵
25	10π	-0,00139663624810749	-0,00026136986950217	8,36.10 ⁻⁷	3,24·10 ⁻⁵

Obviously, functions $\sin(x+y+z)$, $\cos(x+y+z)$ are the functions that belong to a broader class of functions. This suggests that the cubature formula $\Phi^3(\omega)$ has a good approximation accuracy and should be researched on other classes of functions.

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Conclusions

- Report is dedicated to the constructing cubature formulas of approximate calculation of integrals of highly oscillatory functions of two and three variables.
- Cubature formulas are based on Failon method and special operators.
- The feature of the proposed cubature formulas is using the input information about function as a
 - set of traces of function on planes;
 - set of traces of function on lines;
 - set of values of the function in the points.

Conclusions

Thank you for attention!

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